

# Introduction to individual-based modelling: Spatio-temporal models

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Gergely Boza

Institute of Evolution, Centre for Ecological Research (CER), Hungary.

Cooperation and Transformative Governance Group, Advancing Systems Analysis (ASA) Program, IIASA.

Centre for Social Sciences, ELKH, Hungary.

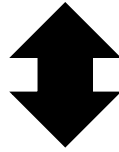
# Contents

- The basics of modelling.
- Components of ABMs/IBMs.
- A little history of ABMs/IBMs.
- Examples (from simple to complex models).
- Challenges and future directions.

## Phenomenological (statistical) models:

The purpose is to **characterize** a pattern or a phenomena, to demonstrate the **relationships** between the relevant variables.

**Top-down**



**Bottom-up**

## Mechanistic models:

The purpose is to understand the underlying **dynamics**, the **processes** and the **mechanisms** that lead to a sort of collective behavior the emergence of a studied pattern or a phenomena.

## Models can be:

- **Scale models**: smaller versions of the target displaying reduction in size and systematic reduction in the level of detail and complexity.
- **Toy models**: some characteristics of the target are extremely simplified in order to allow a deep control of the model.
- **Analogical models**: based on an analogy between the target system and a better understood phenomenon.

**A model is „an ultimate way of asking  
an isolated (specific) scientific question”** JNP

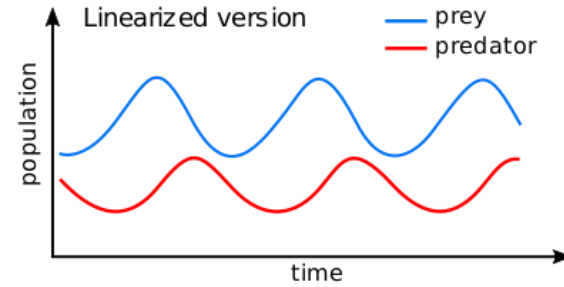
$\frac{dx}{dt}$  ← how a prey population...  
 ← ...changes over time

Model

prey population ( $x$ )  
 predator population ( $y$ )

predation rate ( $\beta$ )  
 consumption rate ( $\gamma$ )  
 death rate ( $\delta$ )  
 growth rate ( $\alpha$ )

Dependent variables  
 Independent variables



Lotka–Volterra (predator–prey) model:  $\frac{dx}{dt} = \alpha x - \beta xy$        $\frac{dy}{dt} = \gamma xy - \delta y$

# Differentiating groups/ subpopulations

Model

preys ( $x_1, x_2, x_3, x_4, \dots, x_N$ )

predators ( $y_1, y_2, \dots, y_N$ )

predation rate ( $\beta$ )

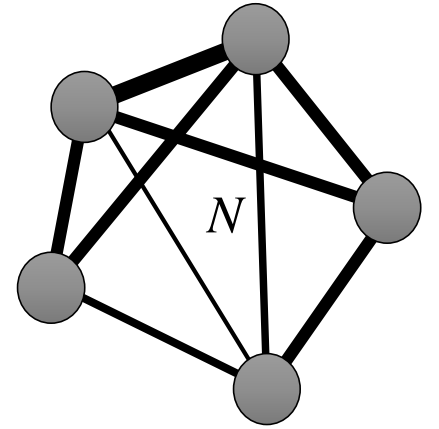
consumption rate ( $\gamma$ )

death rate ( $\delta$ )

growth rate ( $\alpha$ )

dispersal rate

Dependent variables  
Independent variables



# Differentiating individuals **OR** adding complex population structure

Model

Prey 1;  $\alpha_1$

Prey 2 ;  $\alpha_2$

Prey 3 ;  $\alpha_3$

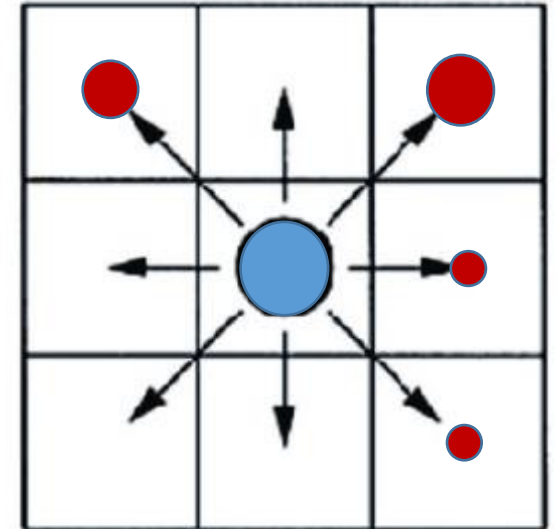
Prey 4 ;  $\alpha_4$

Predator 1;  $\delta_1; \gamma_1$

Predator 2;  $\delta_2; \gamma_2$

Predator 3;  $\delta_3; \gamma_3$

Predator 4;  $\delta_4; \gamma_4$



A(I)BM



# Agent-based models

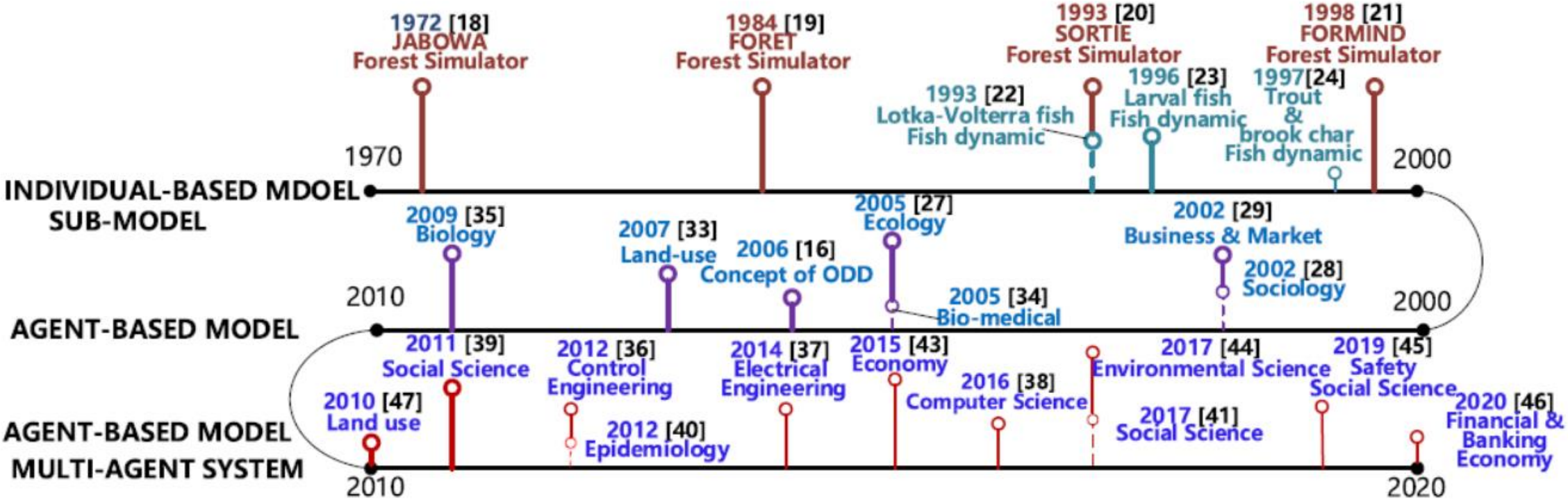
Agent-based modeling is a **computational method** that enables a researcher to **create**, **analyze**, and **experiment** with models composed of **agents** that **interact** within an **environment**.

A form of computational science aiming to capture the essence of the studied system by retaining the **fundamental ingredients** built in a **simplified system** with which we can study the specific questions and problems.

## *A quick terminology*

- Humans, banks, companies, countries → **agent**-based models
- Biological entities → **individual**-based models
- Molecules, compounds, cells → **particle**-based models
- + Multi-agent models (interactions) ↔ Individual-based models (development)
- + Multi-agent systems (complex adaptive systems)
- + Intelligent agents (AI)
- + Cellular Automaton (spatial)

# History of IBMs and ABMs



(Zhang et al. 2021)

# ABM history: the first ABM and the Monte Carlo Method

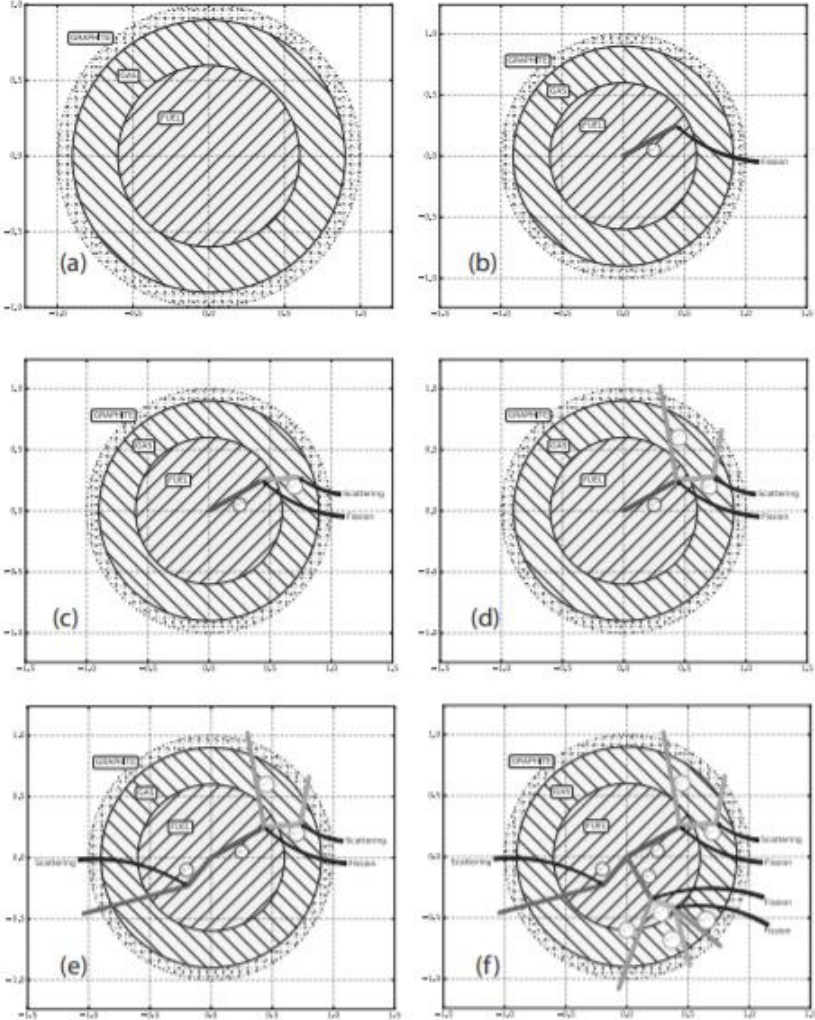
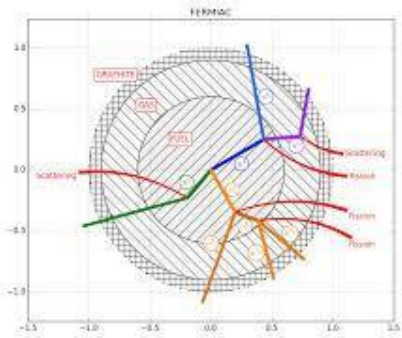
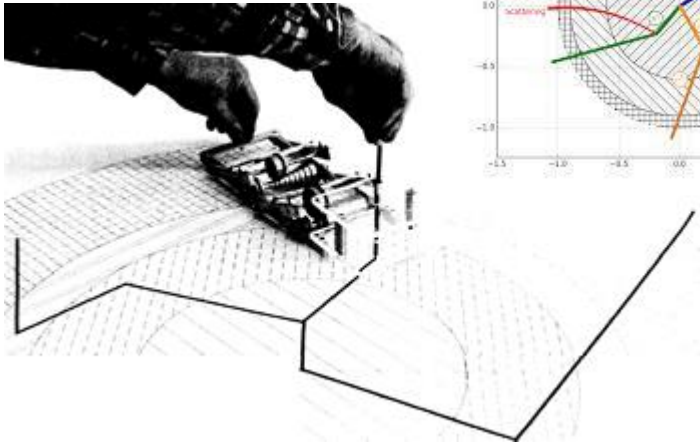
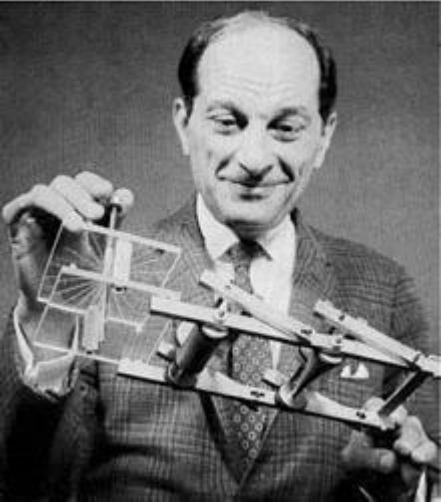
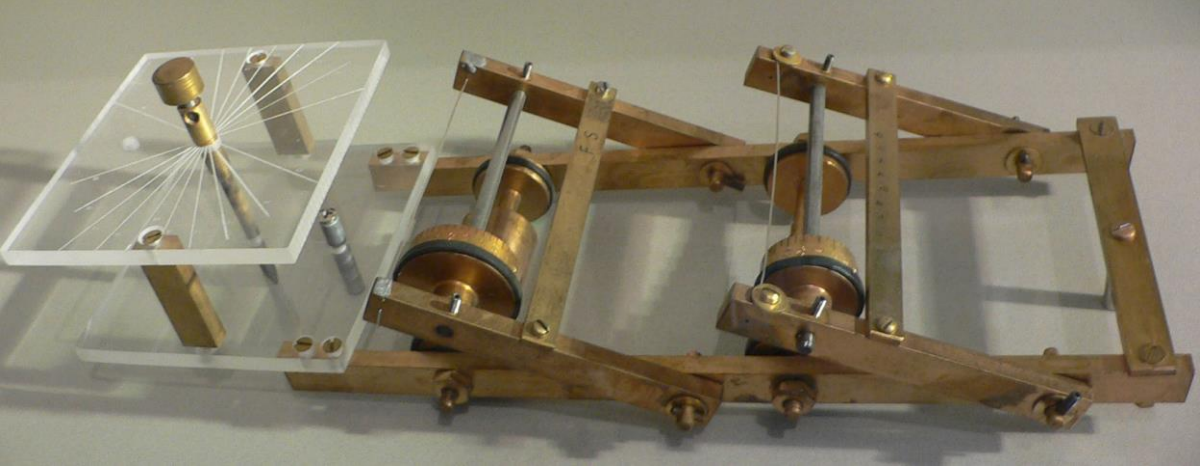
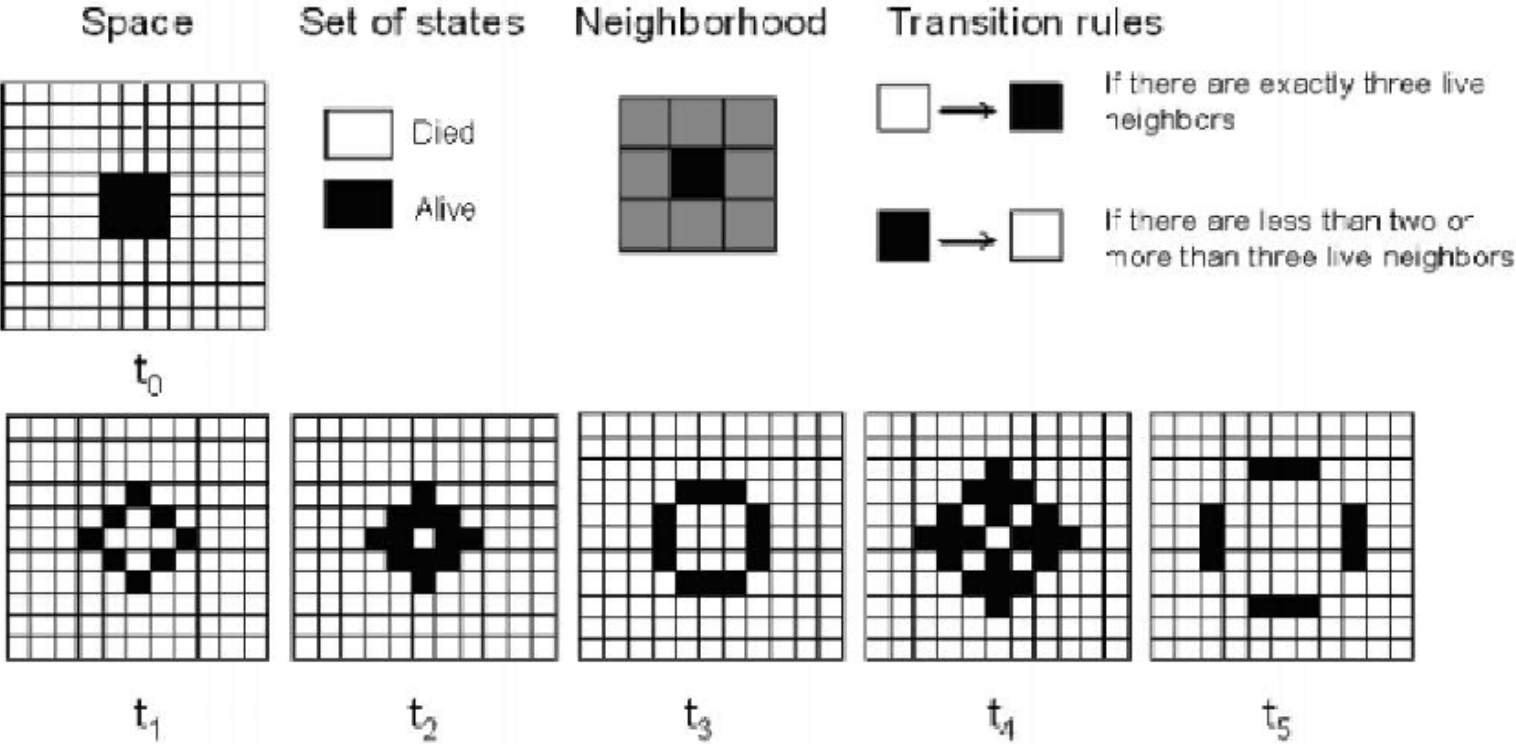


Fig. 6. - An example of the Fermiac used to follow the fate of the genealogy of source neutrons  $n^1, n^2, n^3$  in a cell of a nuclear reactor.

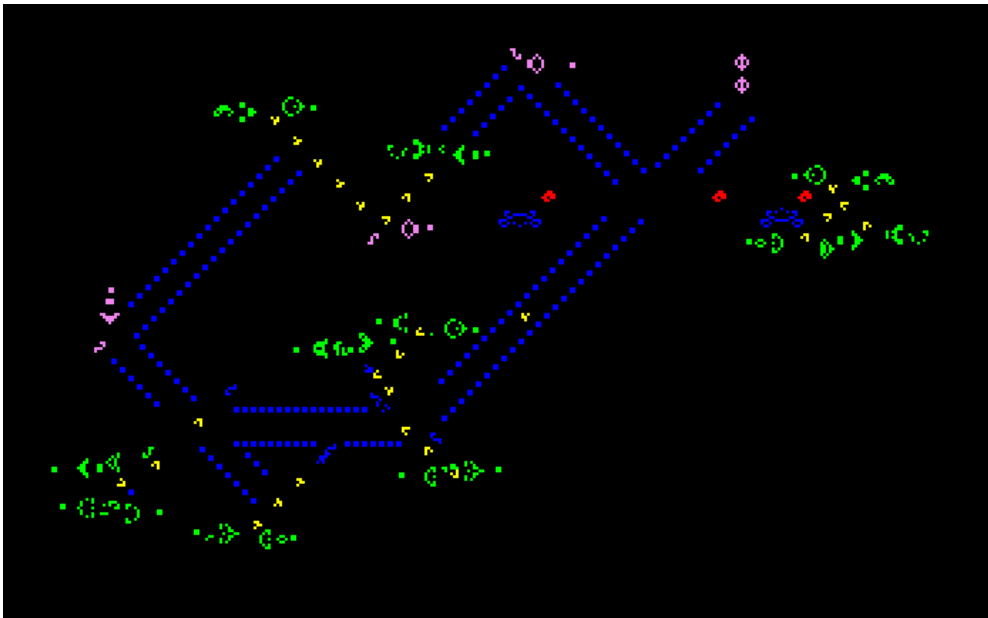
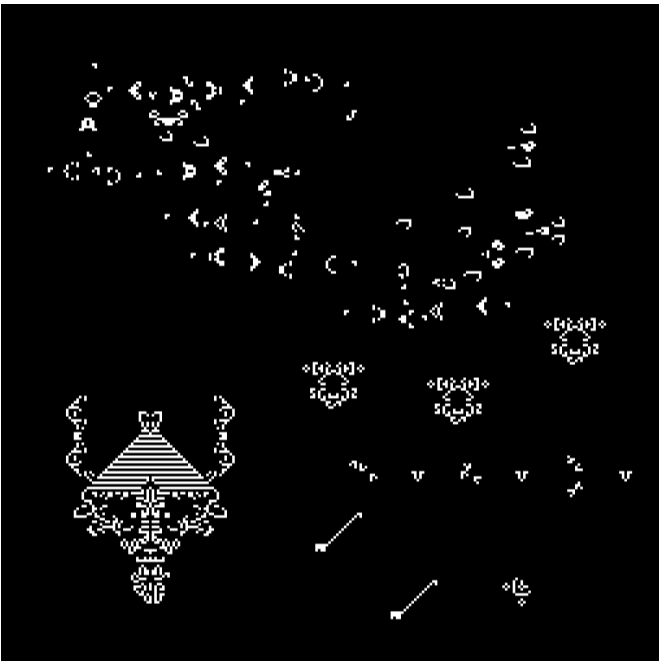
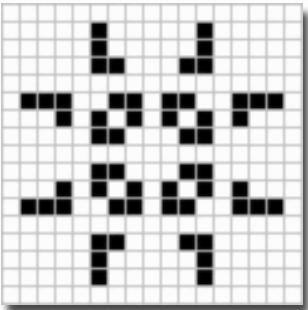
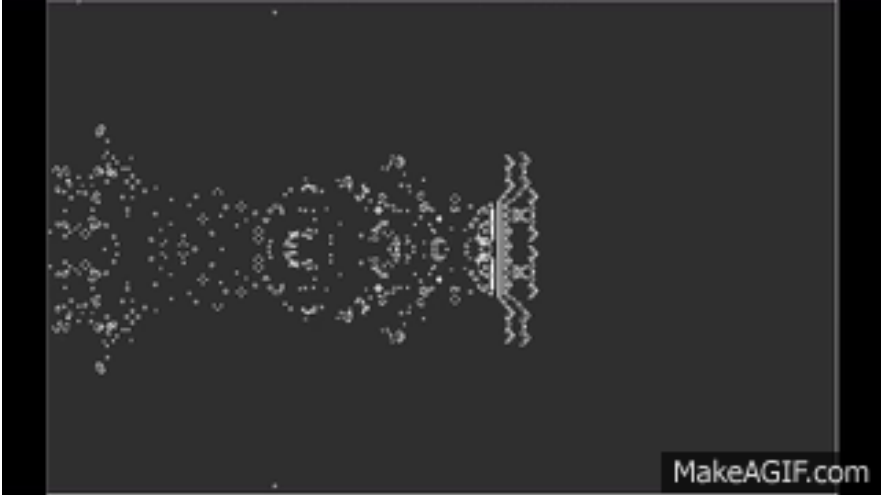
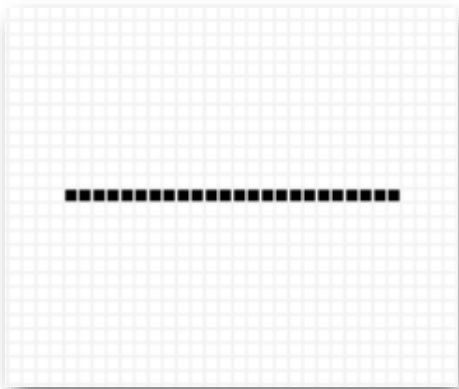
# ABM history: The cellular automaton & Game of Life

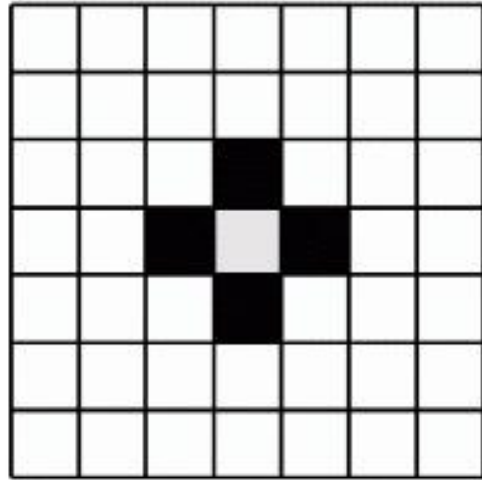
A cellular automaton is a collection of "colored" cells on a grid of specified shape that evolves through a number of discrete time steps according to a set of rules based on the states of neighboring cells.



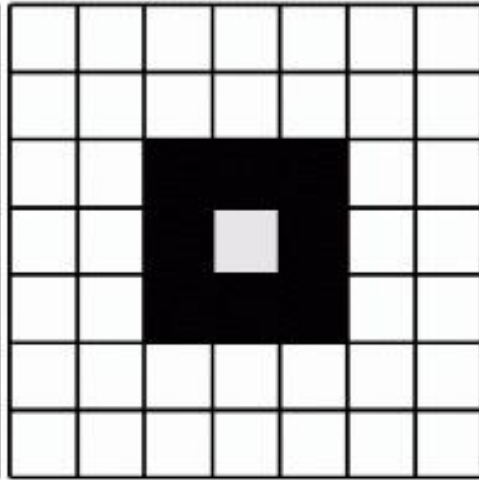
(Turing 1950; von Neumann 1951,1956; Conway 1970; Wolfram 1983; Wahyudi et al. 2015; macleans.ca)

# ABM history: CA & Game of life

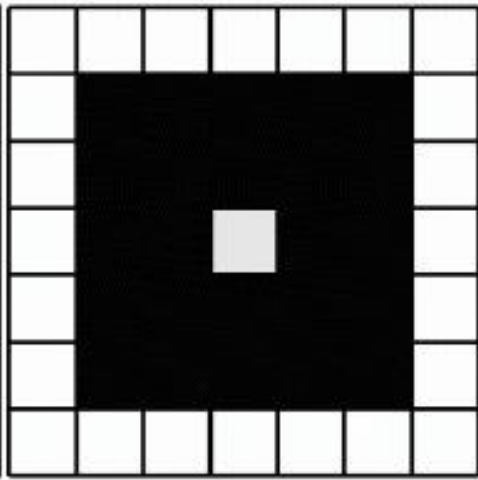




von Neumann  
Neighborhood

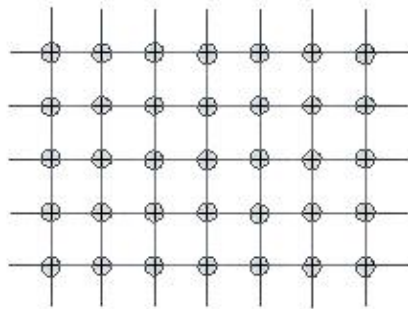


Moore  
Neighborhood

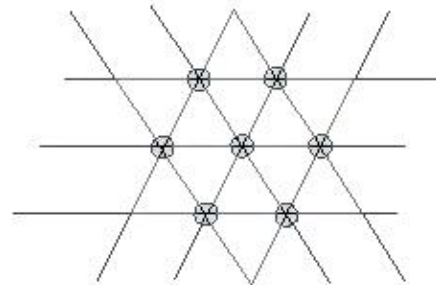


Extended Moore  
Neighborhood

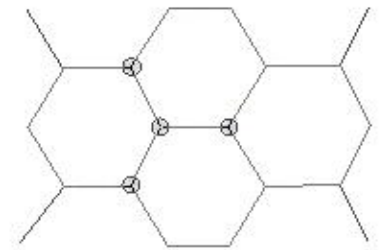
## Two-dimensional Lattice Configurations



Rectangular

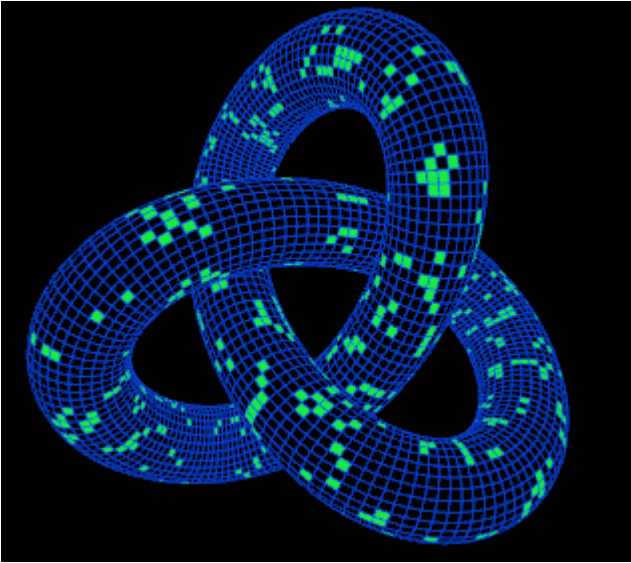
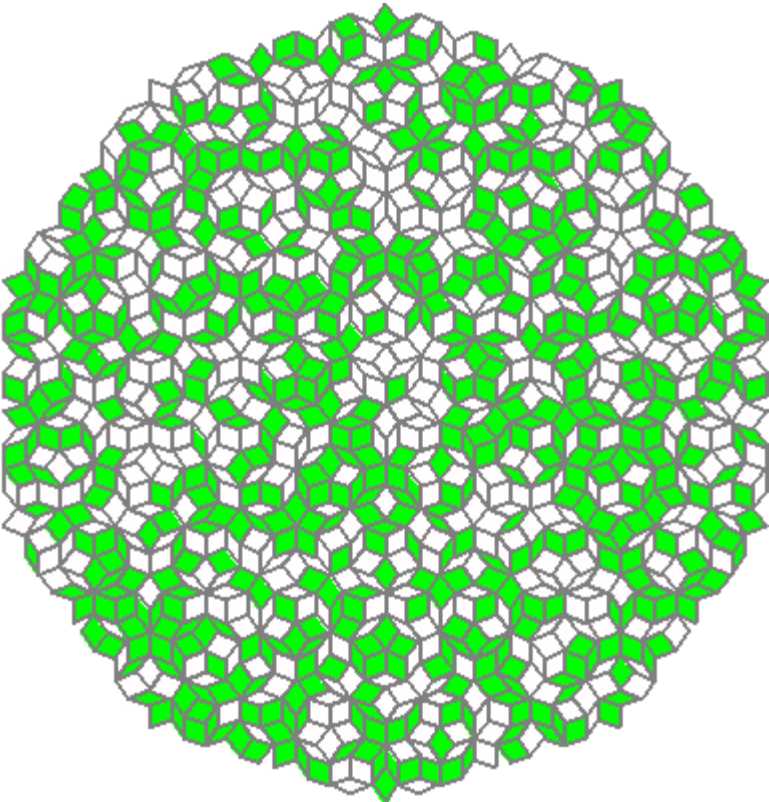
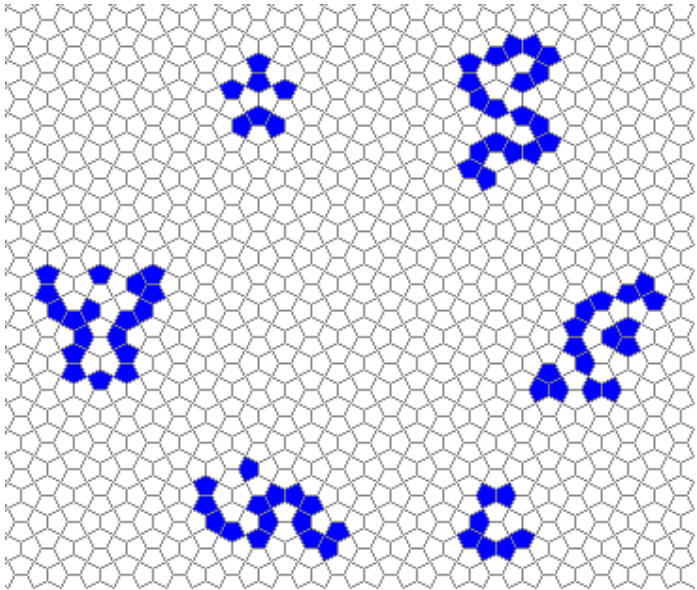
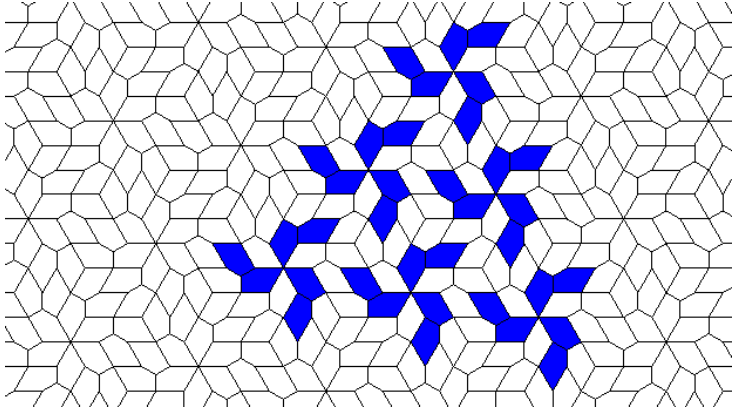
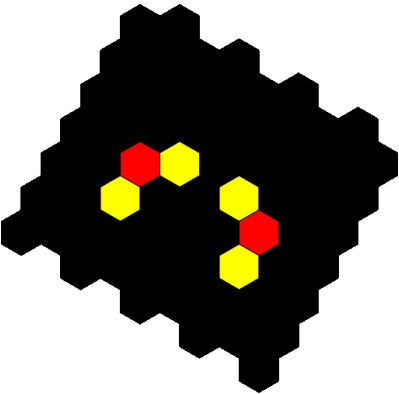


Triangular



Hexagonal

# ABM history: CA & Game of life

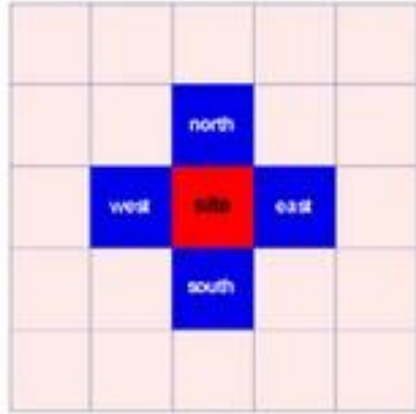


(commons.wikimedia.org; codegolf.stackexchange.com; newbedev.com)



# ABM fundamentals: topology, population structure

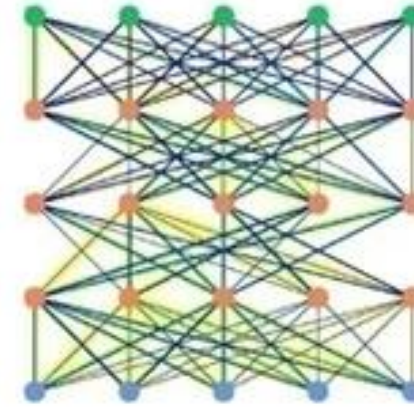
**a**  
Cellular Automata (von Neumann)



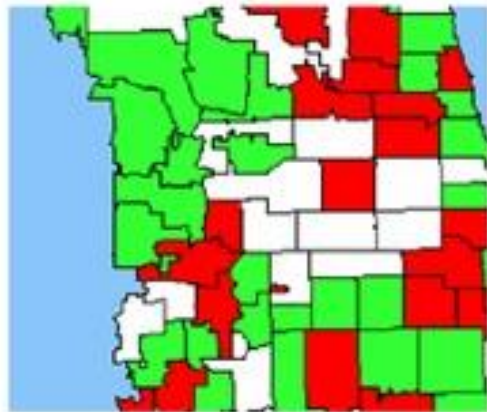
**b**  
Euclidean 2D/3D Space



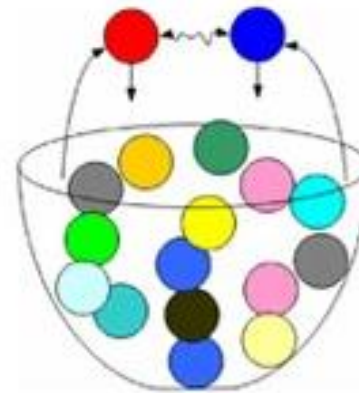
**c**  
Network topology



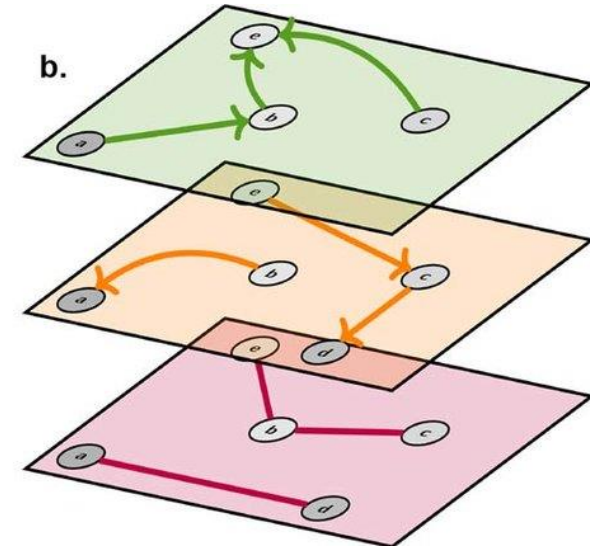
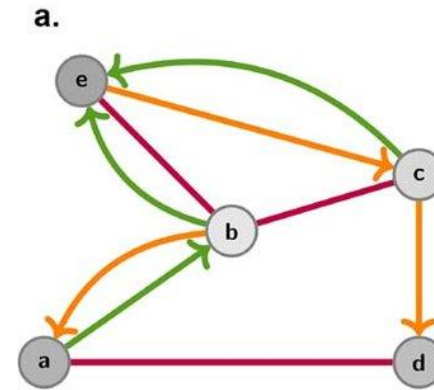
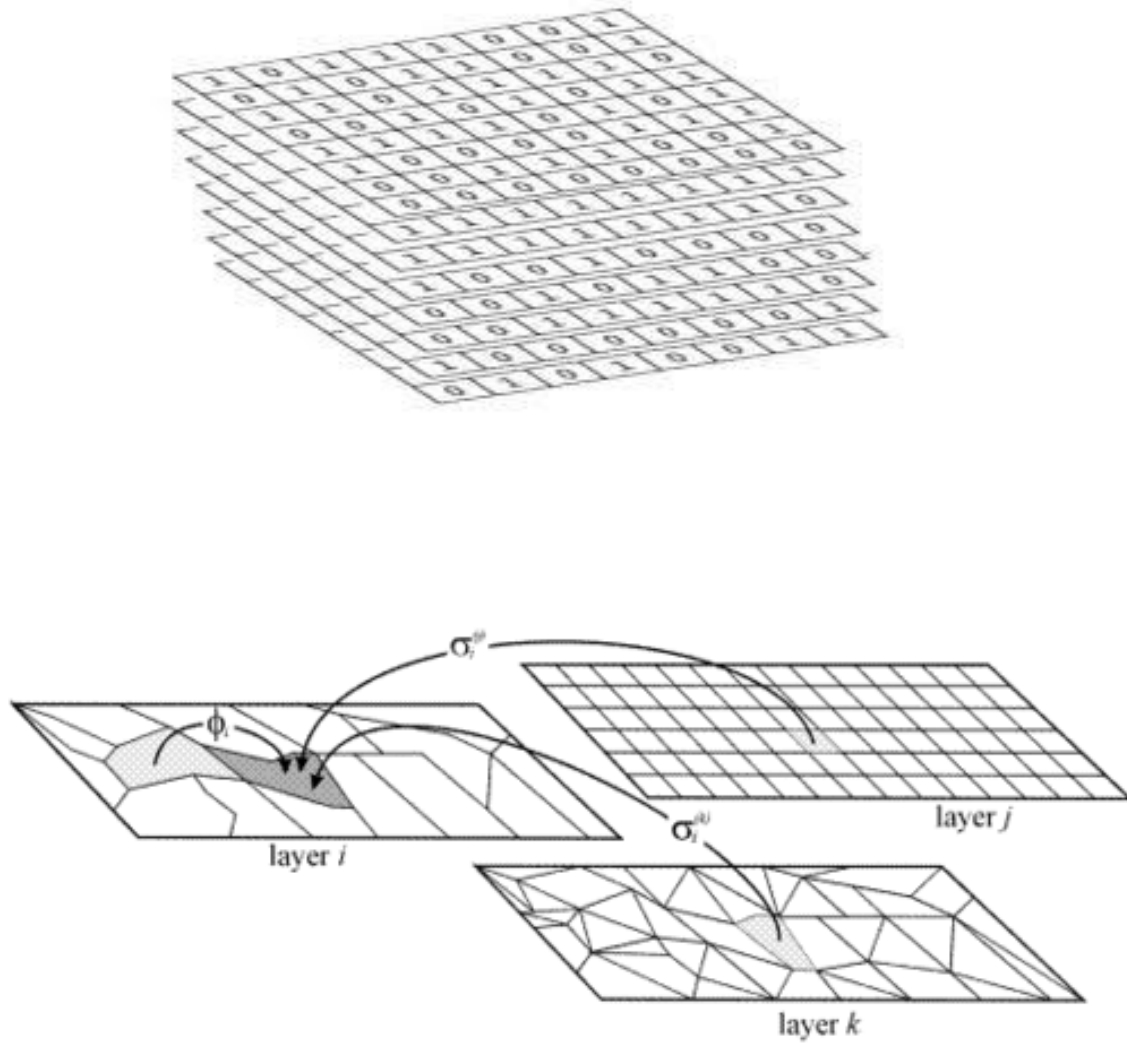
**d**  
Geographic Information System (GIS)



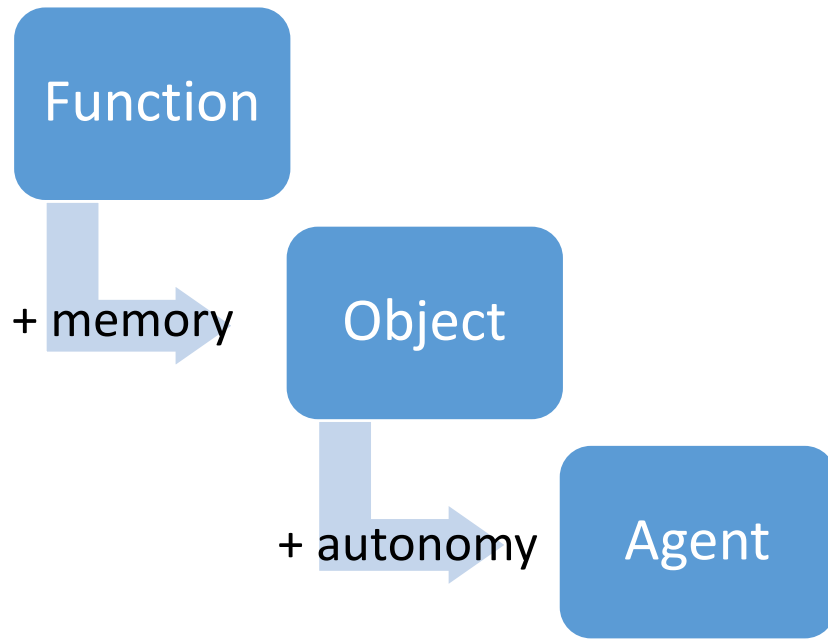
**e**  
"Soup" Model (Aspatial)



# Multi-layer ABM & heterogeneous layers



# What is an *agent*?

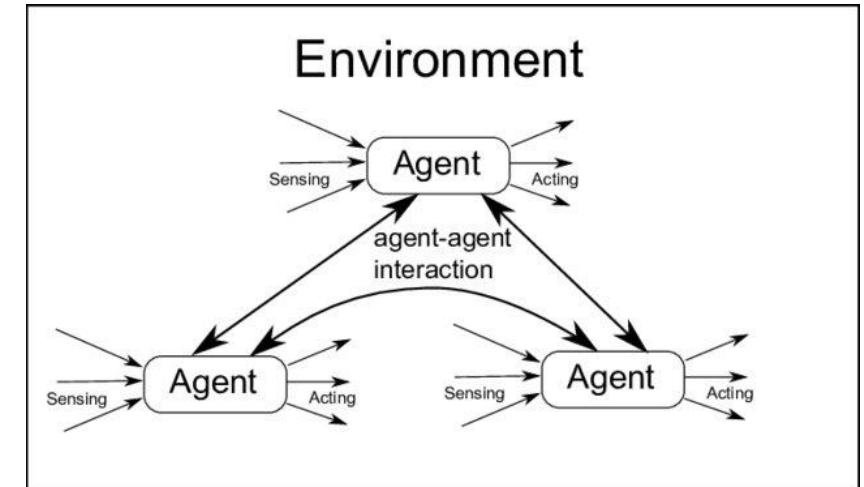
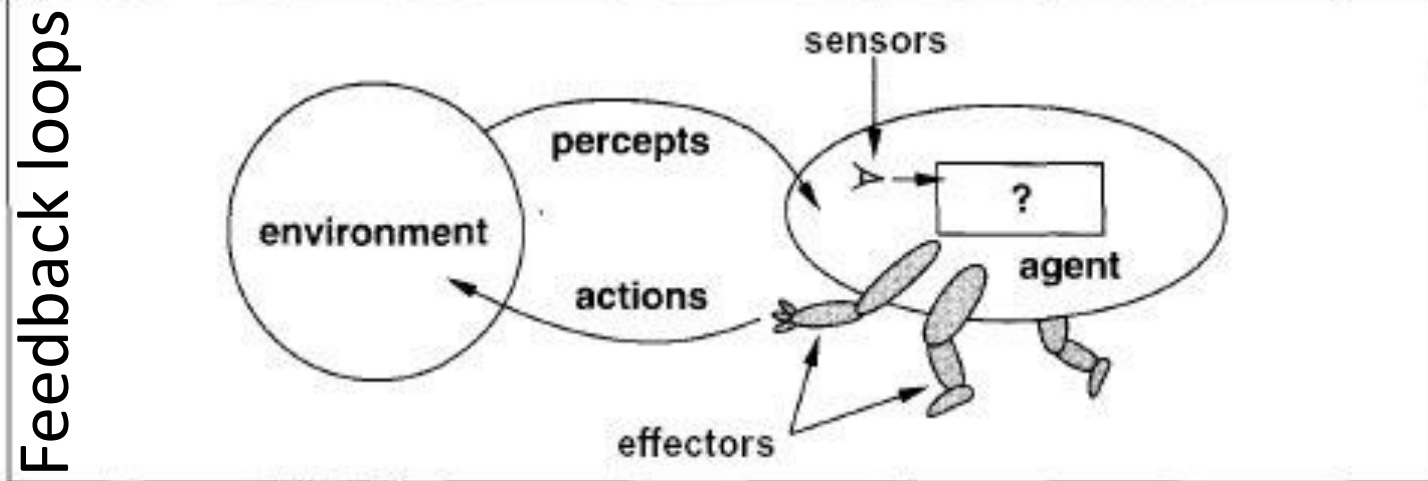


An agent:

- is **self-contained** and unique,
- is **autonomous** and self-directed, has behaviors,
- has a **state** that changes over time,
- is **social** having dynamic interactions;

They can also be:

- adaptive,
- goal-directed
- heterogeneous



# Main features of Agents

- **Autonomy**: simple decision rules
- **Social ability**: interaction between agents
- **Reactivity**: perceive stimuli from others or from the environment
- **Proactivity**: agents have goals

# Main characteristics of Agents

- **Perception**: observe the environment and closeby agents
- **Performance**: react according to a set of behaviors
- **Memory**: storing information about a number of past states, actions
- **Policy**: a set of rules, heuristics, or strategies controlling their response based on the present situation also taking into account their past

## More (potential) features for ABMs

- Large, closed systems
- Flexibility
- Modularity
- Tracking the behavior of each unit through time
- Dynamic system (dep. variables)
- Simple, mechanistic rules
- Agent heterogeneity (no representative agent)
- Bounded rationality, limited knowledge
- Agents have aims, objectives
- Interactions between the agents
- Shared environment
- Interaction/ population / environment structure
- Feed-back between the environment and the agents
- Adaptation, learning (evolutionary, individual, social, imitation)
- Linking different organizational levels
- Scale separation
- Stochasticity, randomness

# ABM fundamentals: state (S) –rule (R) –input (I) architecture

$$A \sim (S,R); S = \{S^1, S^2, \dots, S^k\}; R: (S_t, I_t) \rightarrow S_{t+1}$$

# The dynamics of ABM simulations

- Complex systems
- Stochastic symmetry breaking
- Emergent properties
- Non-equilibrium dynamics and outcomes
- Multi-stable systems, dependency of initial conditions, hysteresis effect
- Phase transitions, tipping points, self-organized criticality, critical phenomena, fat tail events
- Cheap experimenting, *in silico* labs

# Designing an ABM

1 - What specific problem should be solved by the model? What specific questions should the model answer? What value-added would agent-based modelling bring to the problem that other modelling approaches cannot bring?

2 - What should the agents be in the model? Who are the decision makers in the system? What are the entities that have behaviours? What data on agents are simply descriptive (static attributes)? What agent attributes would be calculated endogenously by the model and updated in the agents (dynamic attributes)?

3 - What is the agents' environment? How do the agents interact with the environment? Is an agent's mobility through space an important consideration?

4 - What agent behaviours are of interest? What decisions do the agents make? What behaviours are being acted upon? What actions are being taken by the agents?

5 - How do the agents interact with each other? With the environment? How expansive or focused are agent interactions?

6 - Where might the data come from, especially on agent behaviours, for such a model?

7 - How might you validate the model, especially the agent behaviours?



**Create an environment** in which the agents may interact and make the environment sensitive to actions by the agent.

*Create a virtual space where agents interact according to the defined rules and patterns.*

*Define the feedback loops between the agent and its environment.*

**Create** a population of autonomous **agents** (run-time objects) capable of **making simple decisions in a domain**.

*Create a population of autonomous agents that encapsulate functions, internal memory, and a strategy.*

*Agents can follow different (heterogeneous) or the same (homogeneous) strategy.*

Set-up agent **relationships** and the modes of interaction.

*Define the underlying topology of connectedness> who interacts with whom, and driven by what rules?*

Define the **update rules**. Define the algorithm by which the different components (functions) of your model will be evaluated.

*Determine the mode and sequence of updating the population of agents and the environment.*

*Define what rules apply for the elementary processes in the system, such as death, survival, proliferation, reproduction, migration, production, consumption/feeding, etc.*

Determine the **dependent** and **independent variables** of the system, the **static** and the **dynamic** attributes.

*Independent → the cause: input (controlled, explanatory) – Dependent → the effect: output (response).*

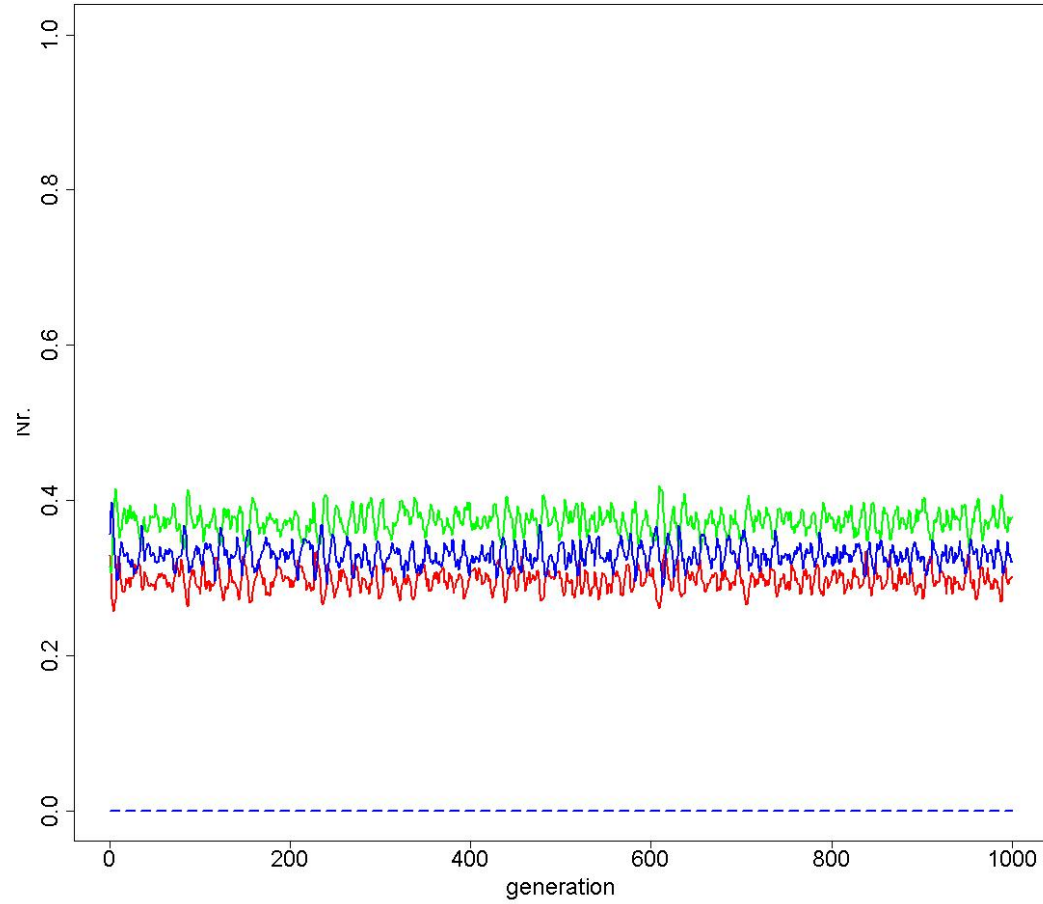
*What can change and what is kept constant, unchanged during a simulation run and what changes?*

**Initialize** the model, allow the agents to operate autonomously, and observe for emergent complex phenomena.

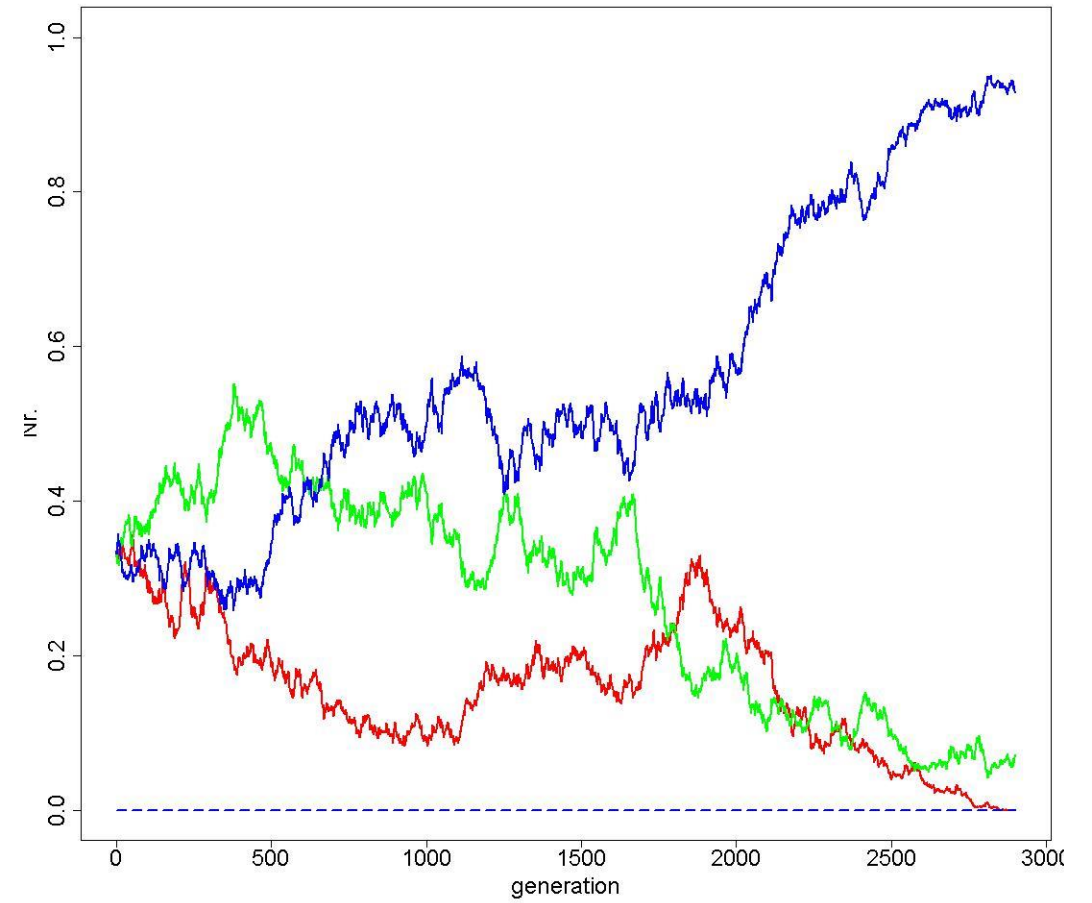
**Run the simulation**. Allow the agents to **act** and to **adapt** to their changing („abiotic”, „biotic”, „social”) environment through mechanisms such as evolutionary, learning or optimization algorithms.

# Update

## Synchronous

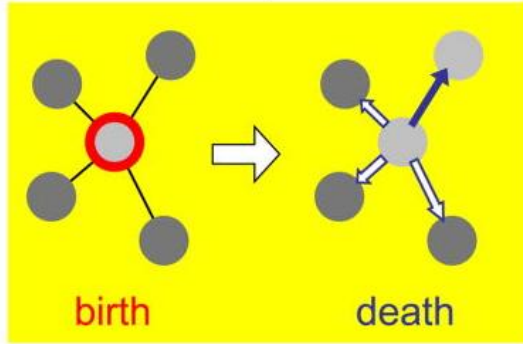


## Asynchronous

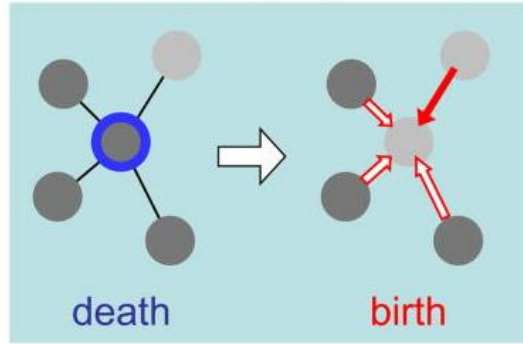


# Update rules

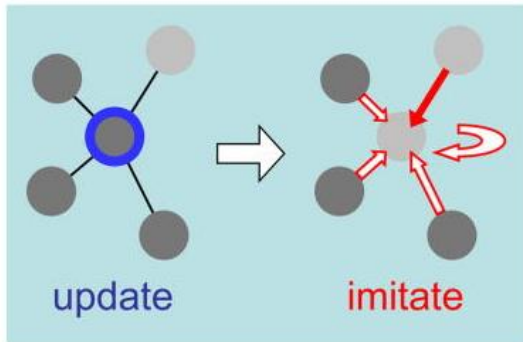
a. Birth-death (BD)



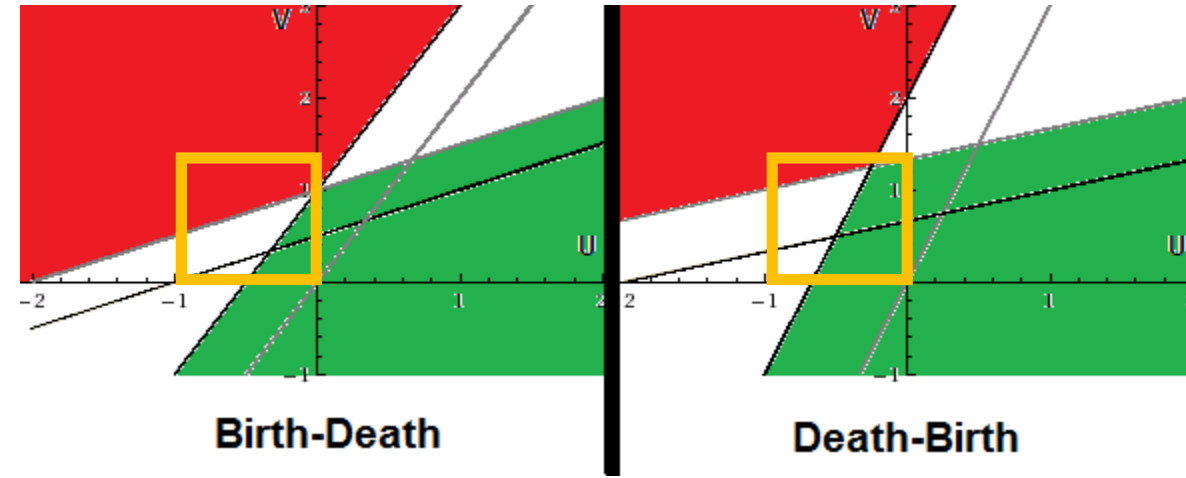
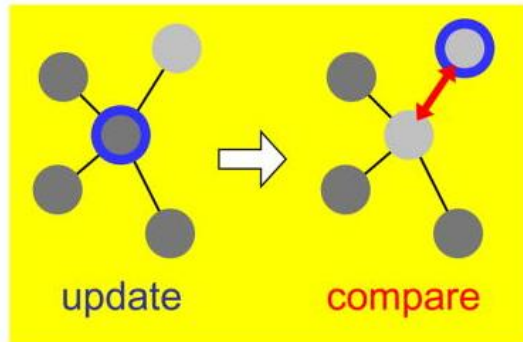
b. Death-birth (DB)



c. Imitation (IM)



d. Pairwise comparison (PC)

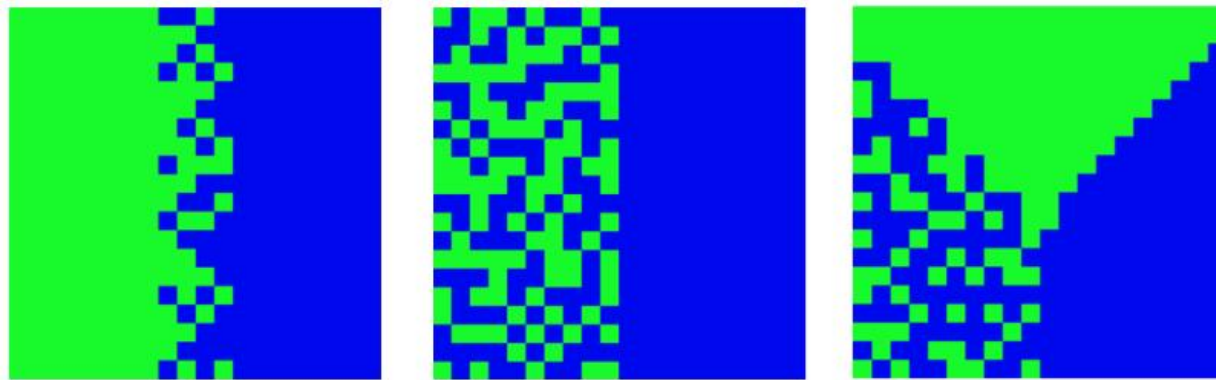
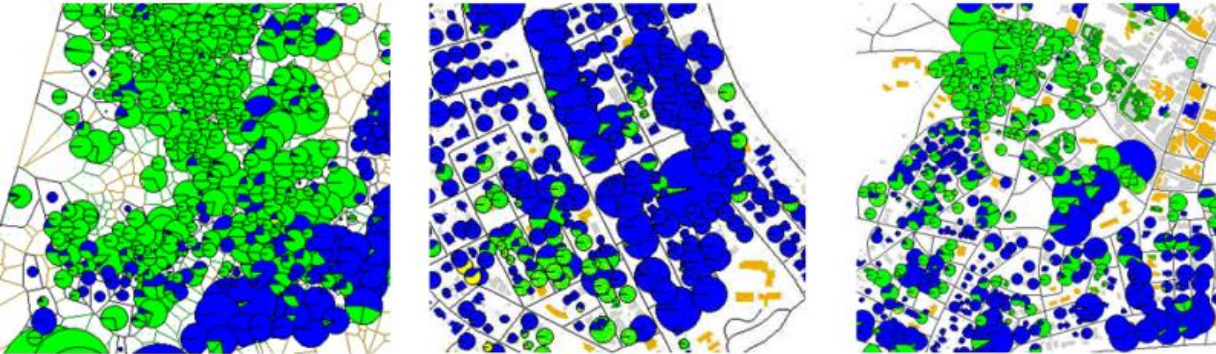


BD and PC updates promote defection  
 DB and IM updates promote cooperation

**A few examples**

# ABM history- Socio-economic systems: A model of segregation (Schelling 1969)

## & 2D Ising model



(a)

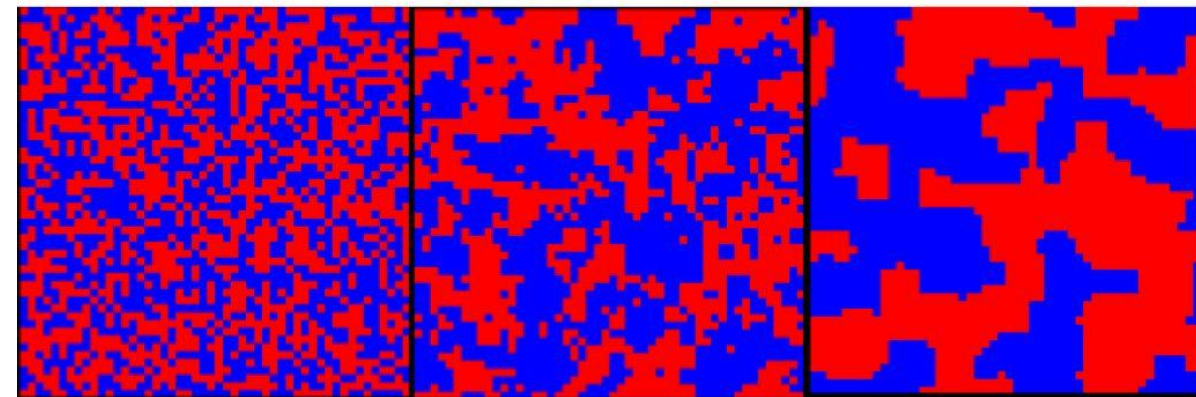
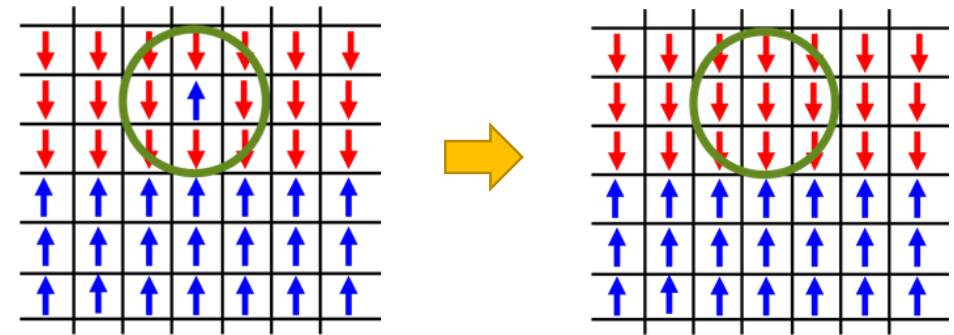
(b)

(c)

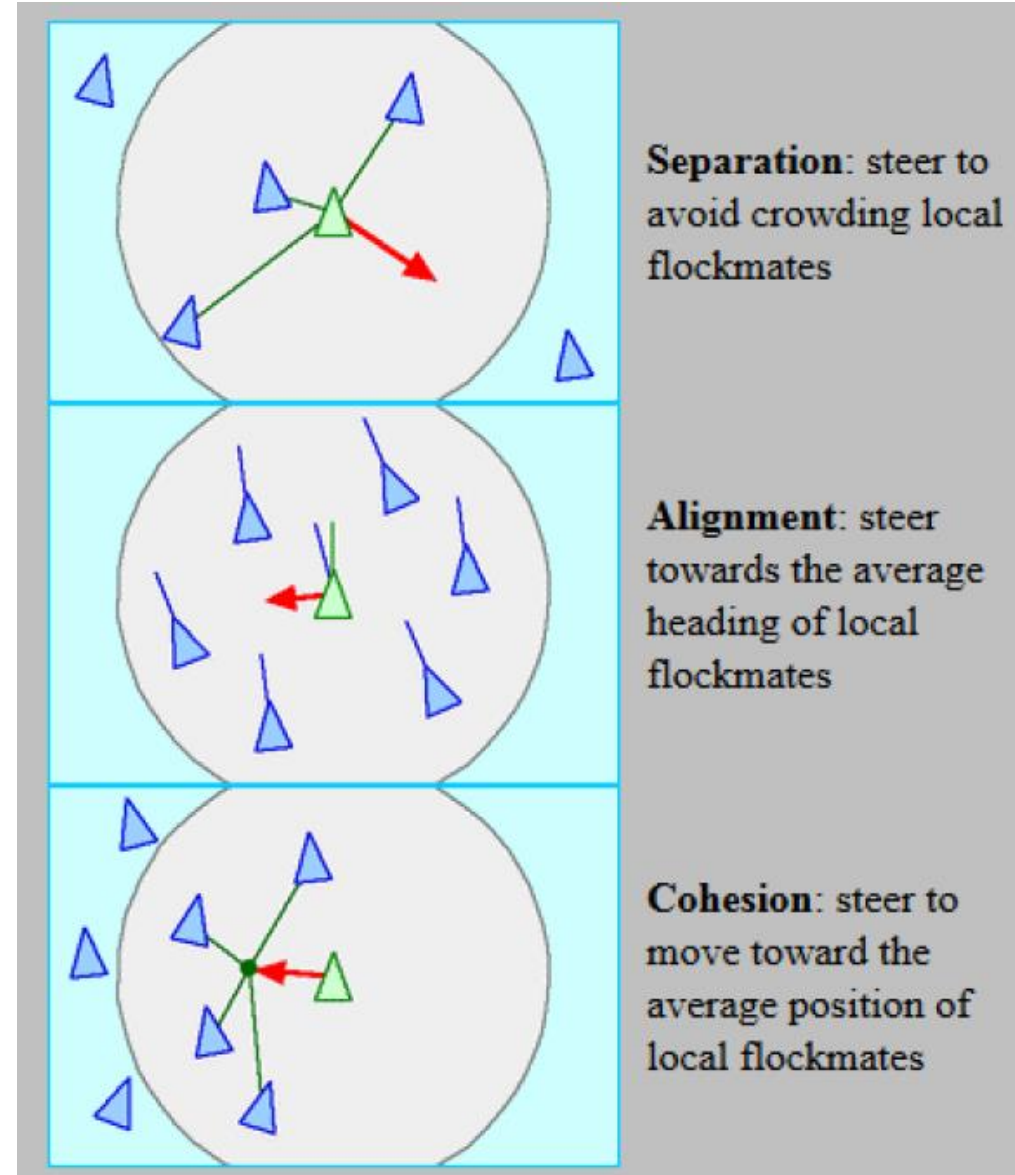
Simple rules:

- look around
- relocate if not satisfied (many other types are around).

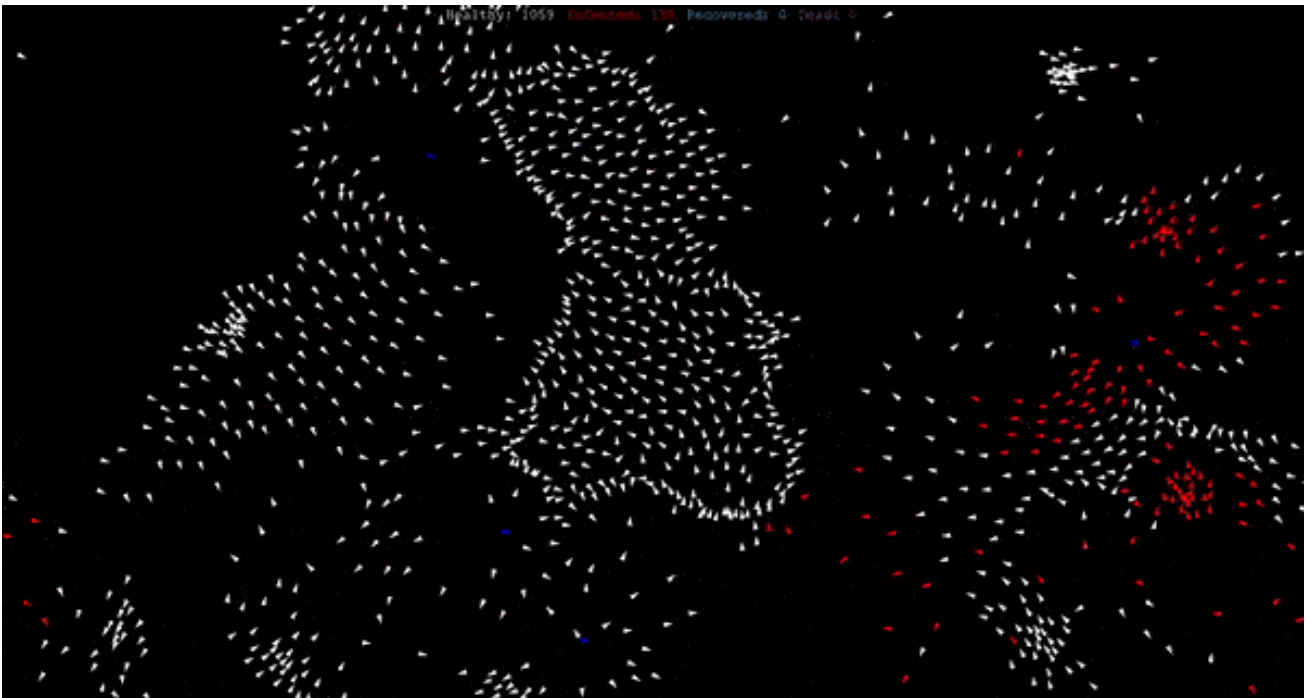
Yet, can explain observed, real-life patterns



# ABM history – Biology: The flocking model



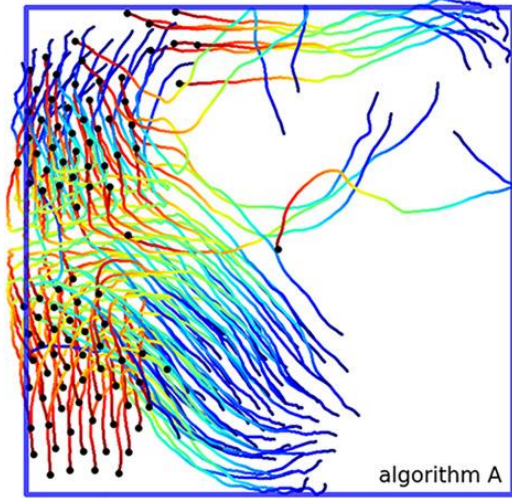
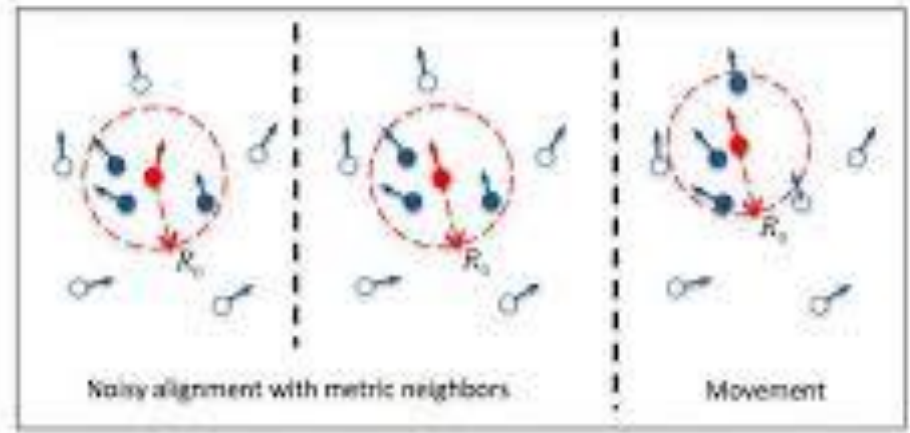
# ABM history – Biology: The flocking model



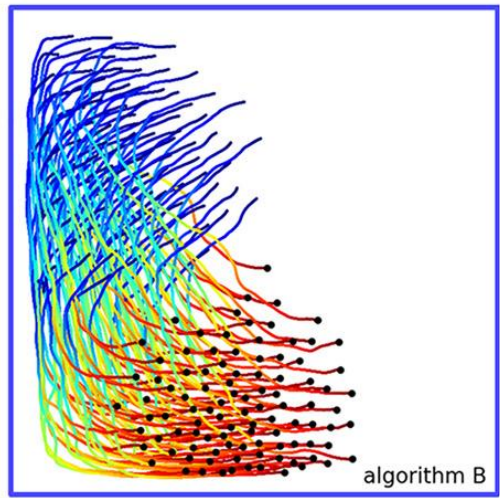
# ABM history - Biology

## The flocking model & real-life use

A



algorithm A



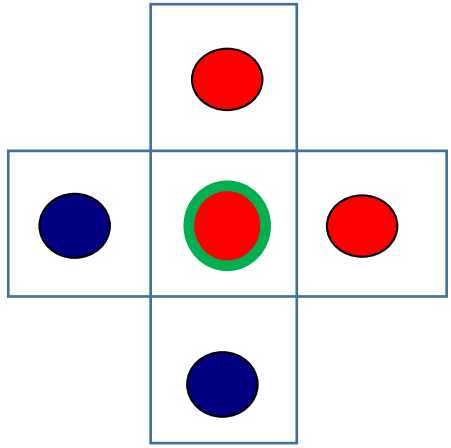
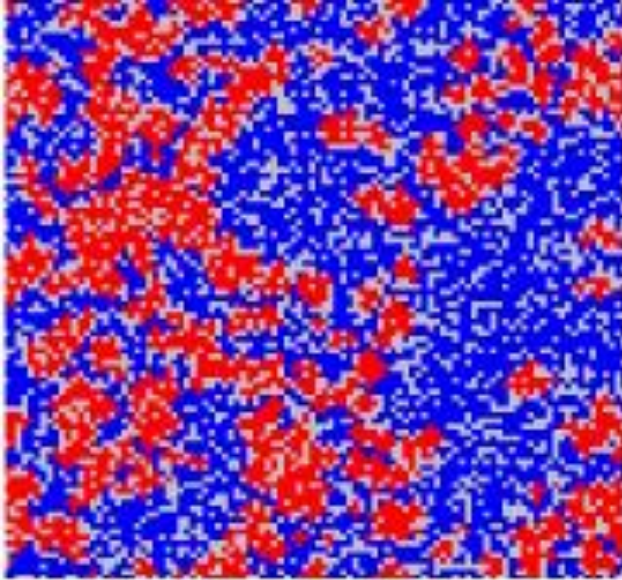
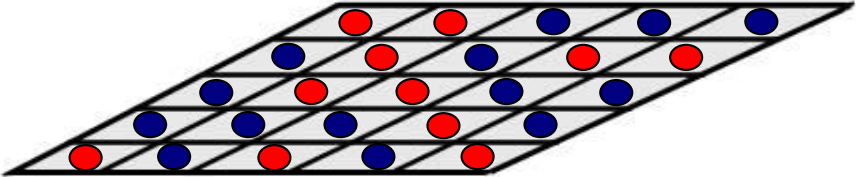
algorithm B



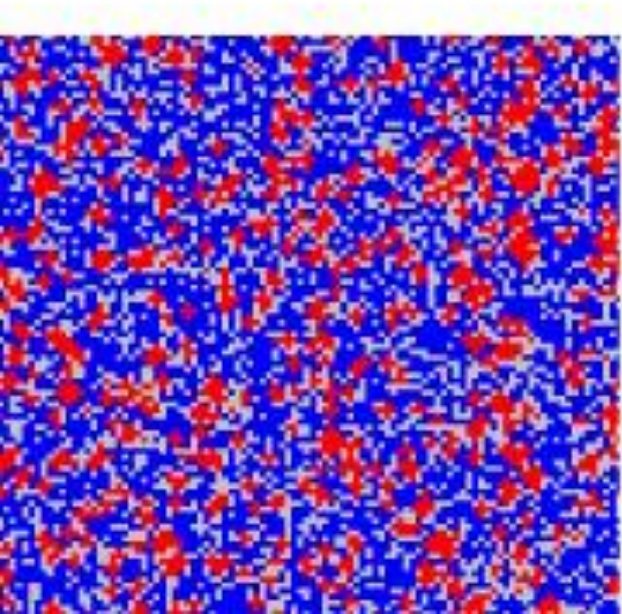
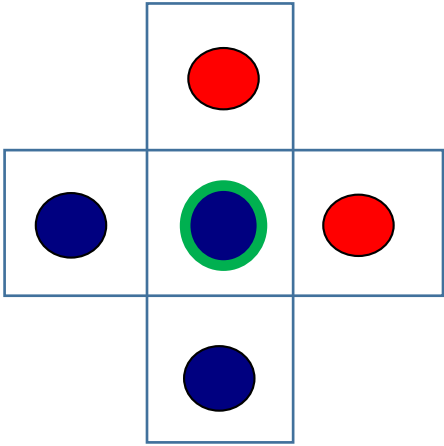


# ABM & Game theory

- = cooperators / producers
- = defectors / free-riders

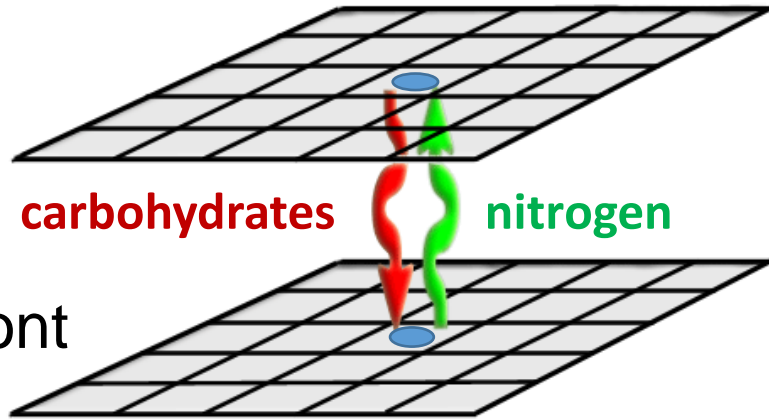


		NEIGHBOR	
		●	●
FOCAL	●	3	0
	●	5	1

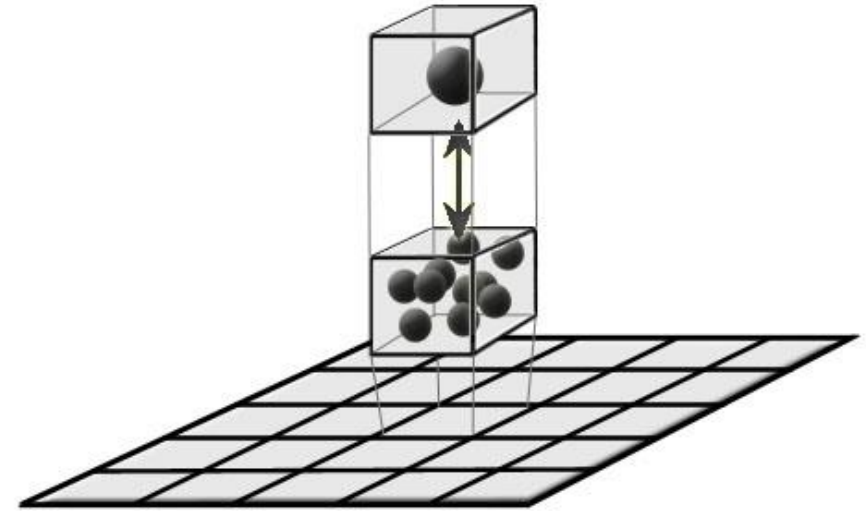


# IBM & Inter-species mutualism

Agent I: host

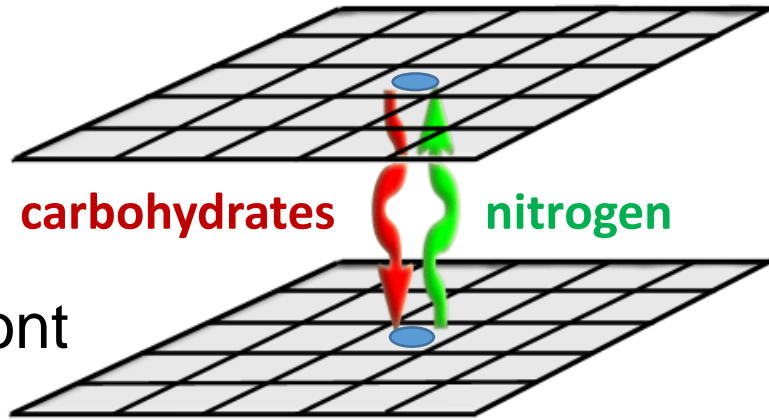


Agent II: symbiont



# IBM & Game theory with two types of agents

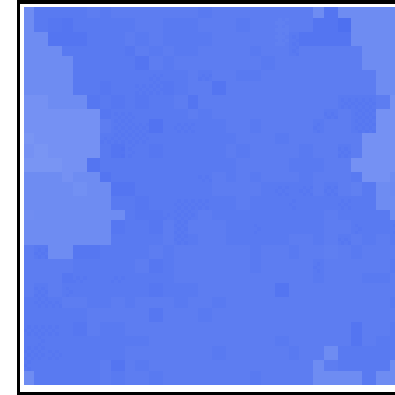
Agent I: host



Agent II: symbiont

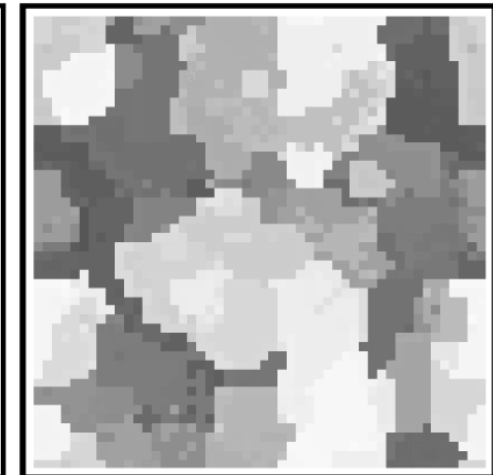
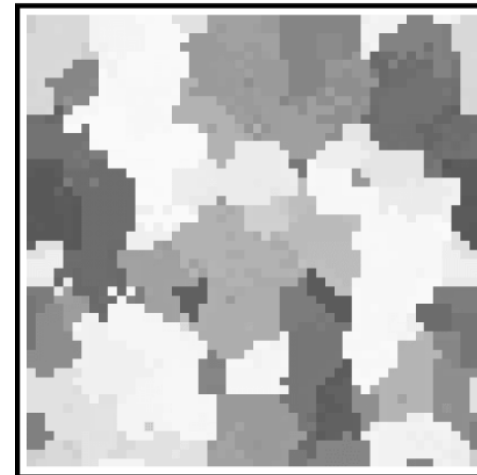
Host

Symbiont



Mutualist A

Mutualist B

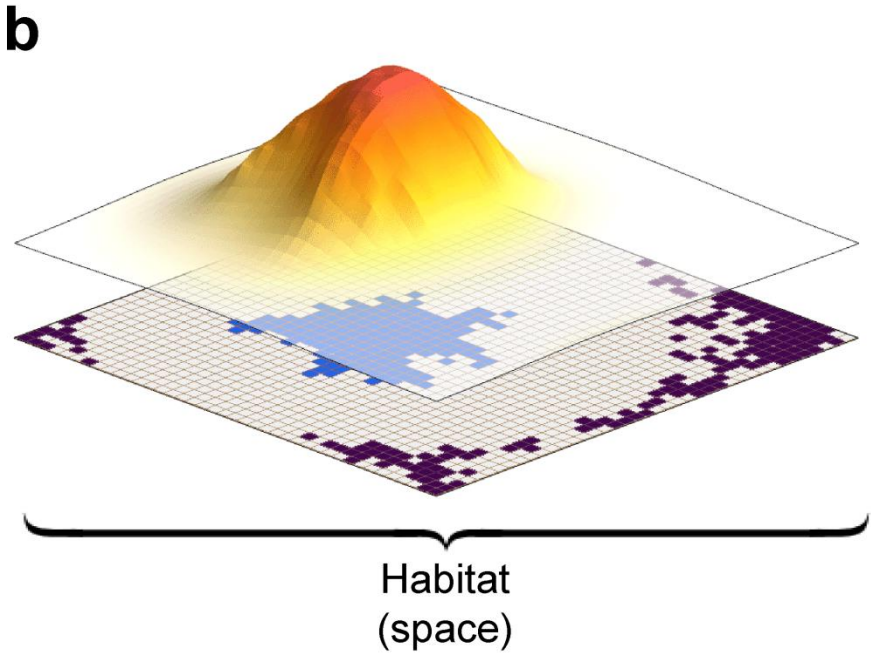
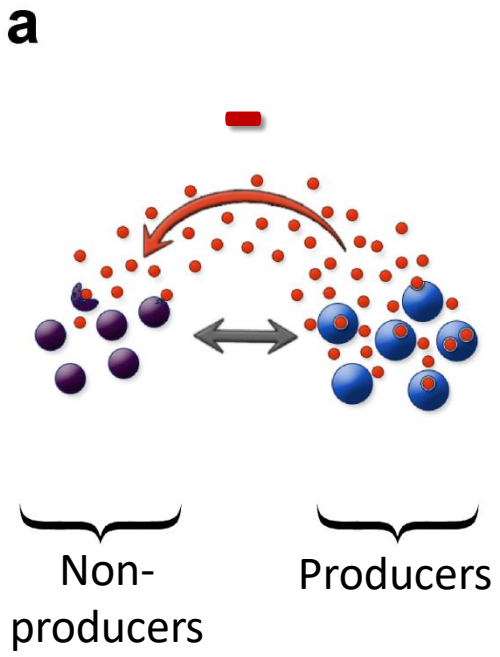


max



min

# IBM & particle-based modelling



# IBM & particle-based modelling

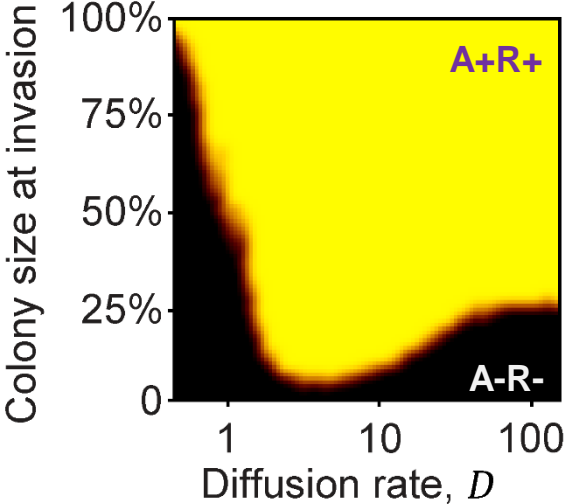
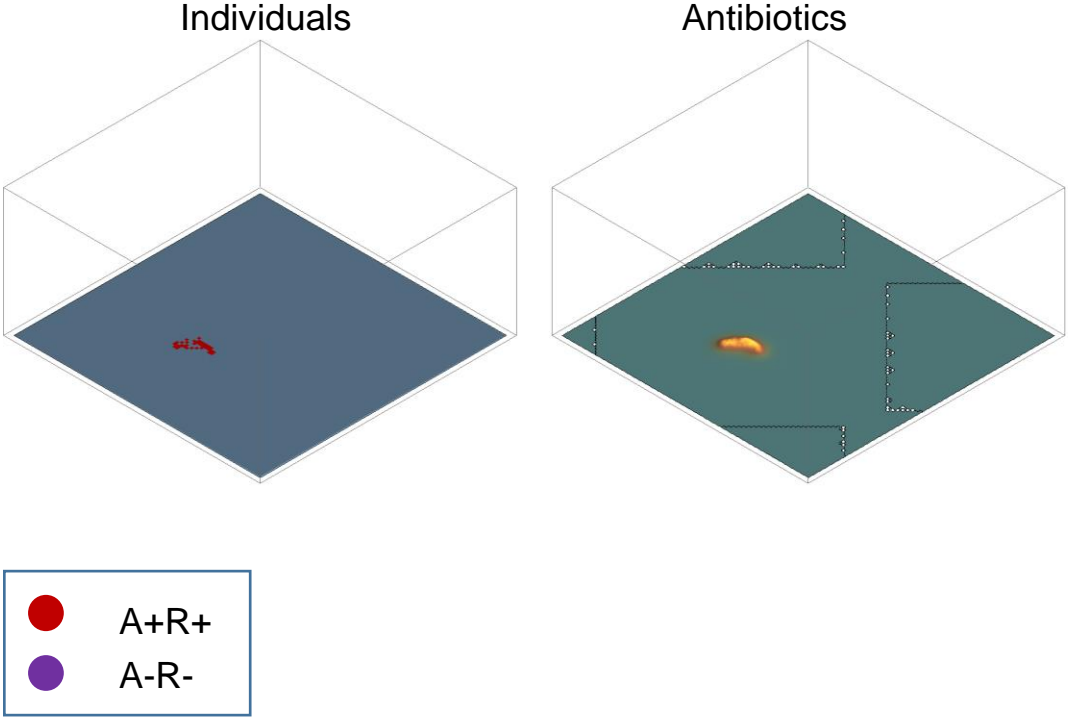
## Dynamics of the **antibiotics** in the environment

$$A^{\text{Ext}}(i, t + \Delta t) = A^{\text{Ext}}(i, t) + \left[ \underbrace{\frac{D}{\Delta x^2} \left( \sum_{j=1}^v A^{\text{Ext}}(j, t) - v A^{\text{Ext}}(i, t) \right)}_{\text{diffusion}} + \underbrace{(\rho_*(t))}_{\text{production}} + \underbrace{\beta_* A^{\text{Int}}(i, t)}_{\text{cellular efflux}} - \underbrace{\alpha_* A^{\text{Ext}}(i, t)}_{\text{cellular uptake}} - \underbrace{\varphi A^{\text{Ext}}(i, t)}_{\text{decay}} \right] \theta(i) \Delta t$$

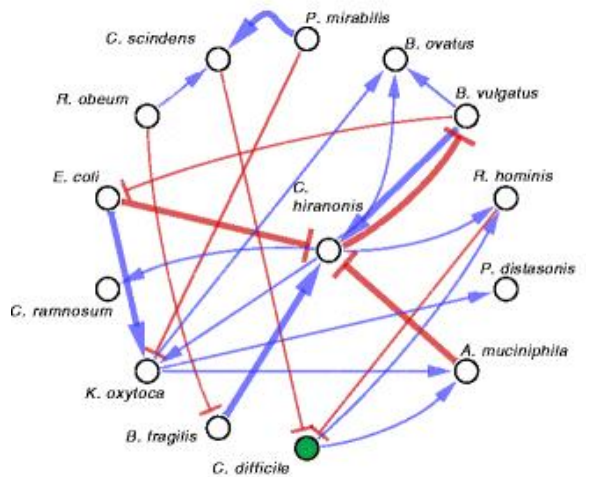
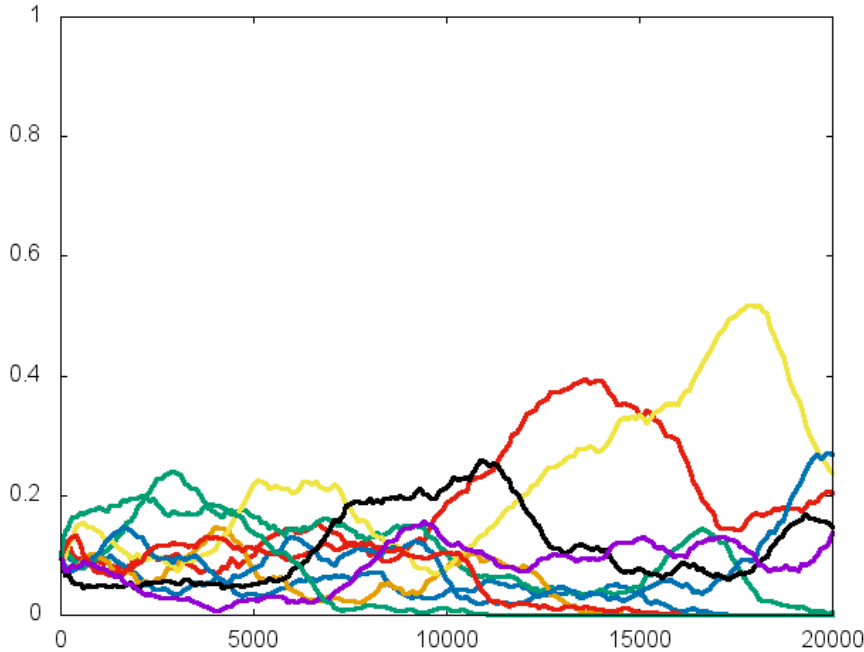
## Intracellular dynamics of the **antibiotics**

$$A^{\text{Int}}(i, t + \Delta t) = A^{\text{Int}}(i, t) + \left( \underbrace{\alpha_* A^{\text{Ext}}(i, t)}_{\text{cellular uptake}} - \underbrace{\beta_* A^{\text{Int}}(i, t)}_{\text{cellular efflux}} - \underbrace{\gamma_* A^{\text{Int}}(i, t)}_{\text{decomposition}} \right) \Delta t$$













# IBM & particle-based modelling



# IBM & interaction networks & particle-based modelling



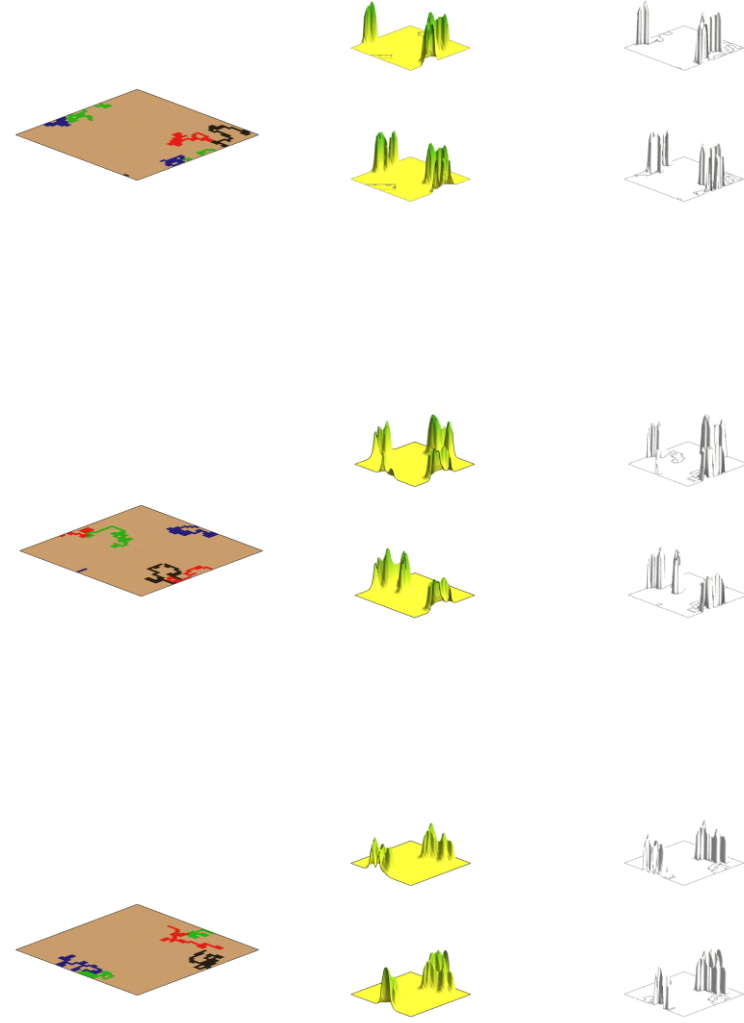
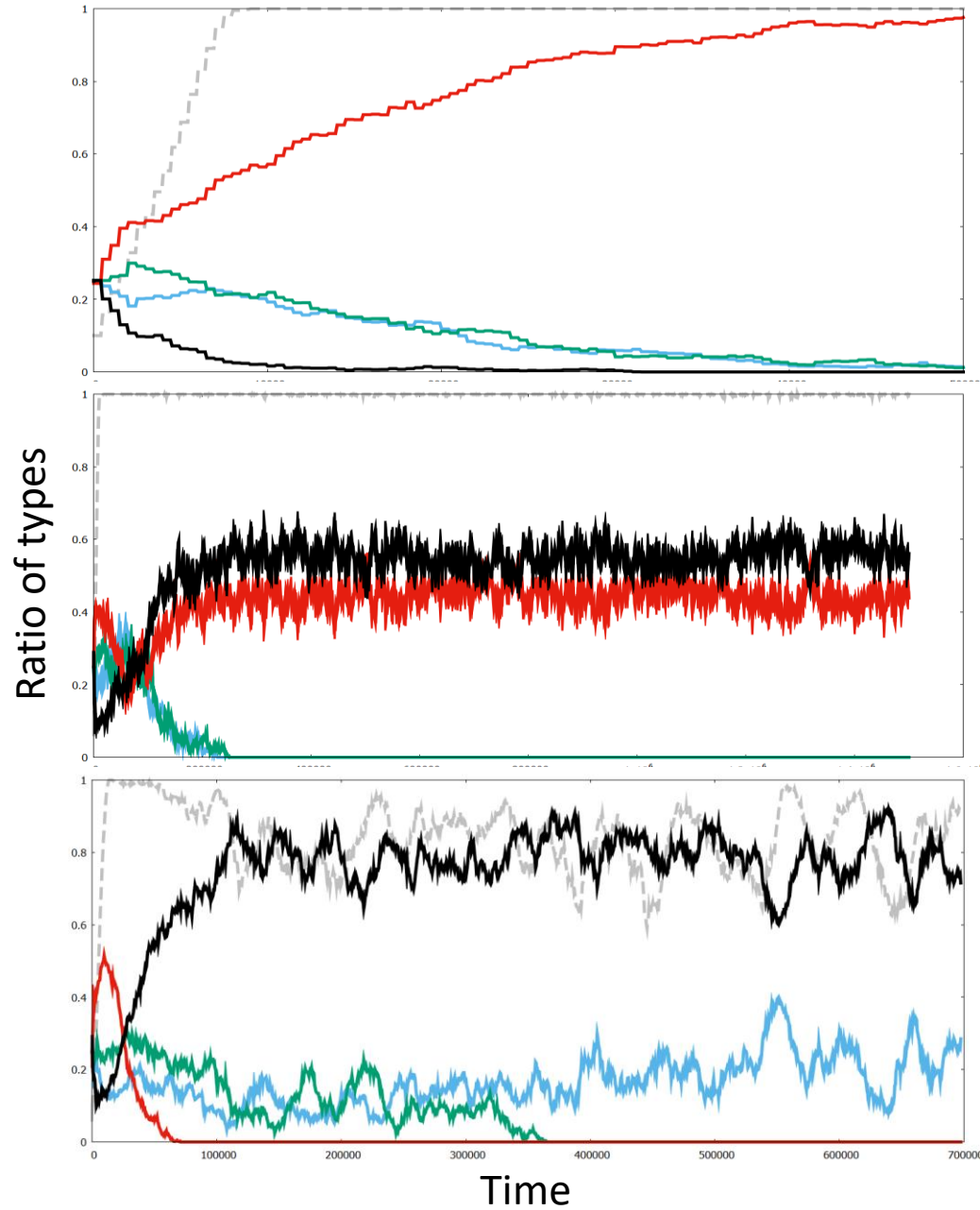
# IBM & Cross-feeding: **Specialists** – **Generalist** – **Free-rider** population dynamics

Species	Diffusible resource produced (Public good)		Cost of producing	Growth effect of the resource: Mutualism (1)
	PG 1	PG 2		
	→ 	→ 	-c	<b>1</b>
	→ 	→ 	-c	<b>1</b>
	→ 	→ 	-2c	<b>1</b>
	→ 	→ 	0	<b>1</b>

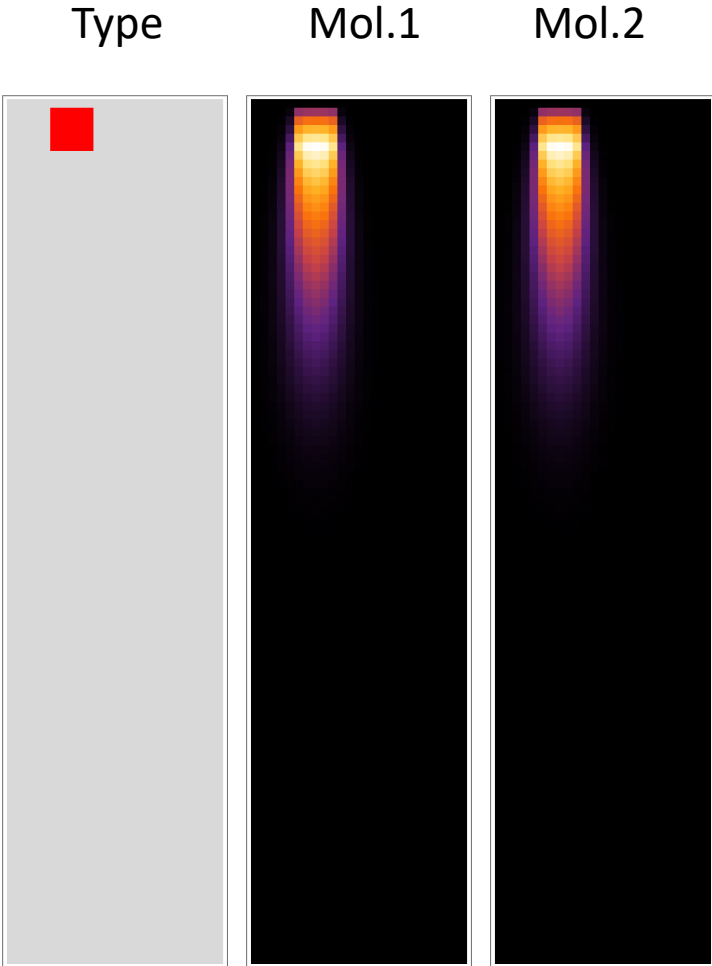
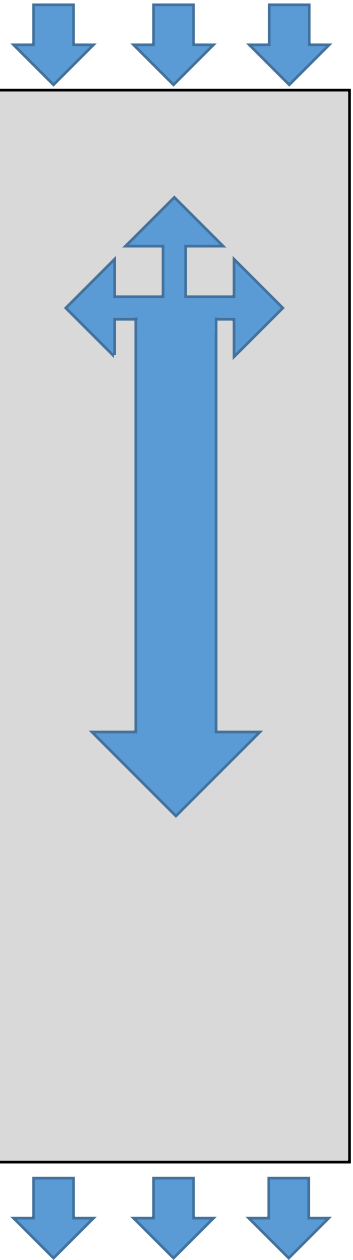
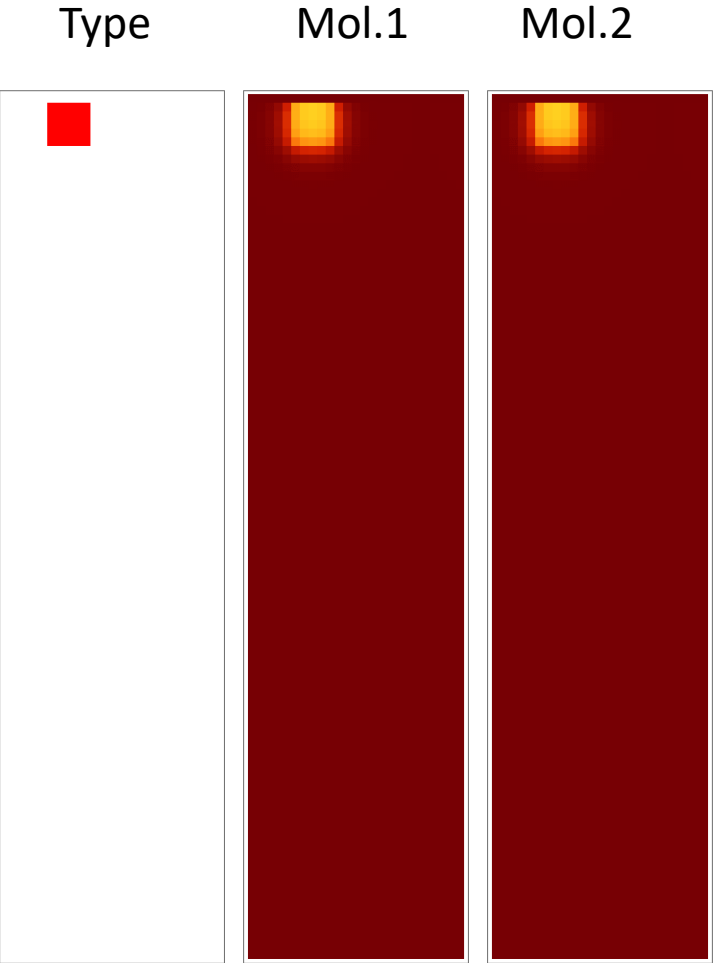
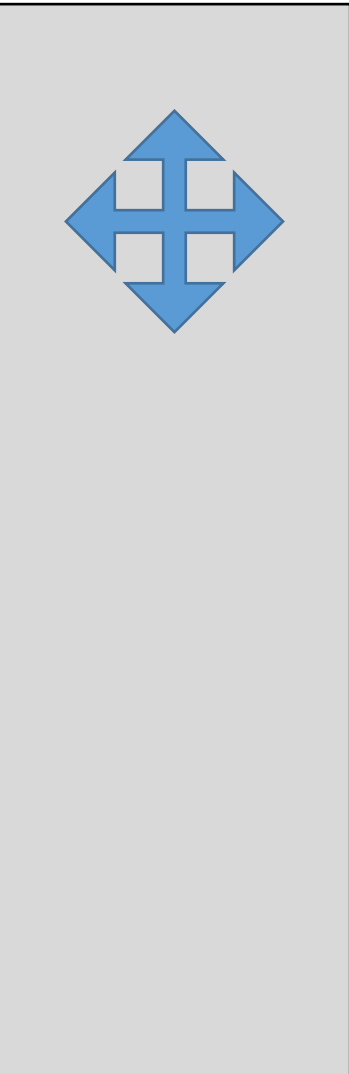


# IBM & Cross-feeding: **Specialists** – **Generalist** – Free-rider population dynamics

Diffusion rate increases















# IBM & Gradient model



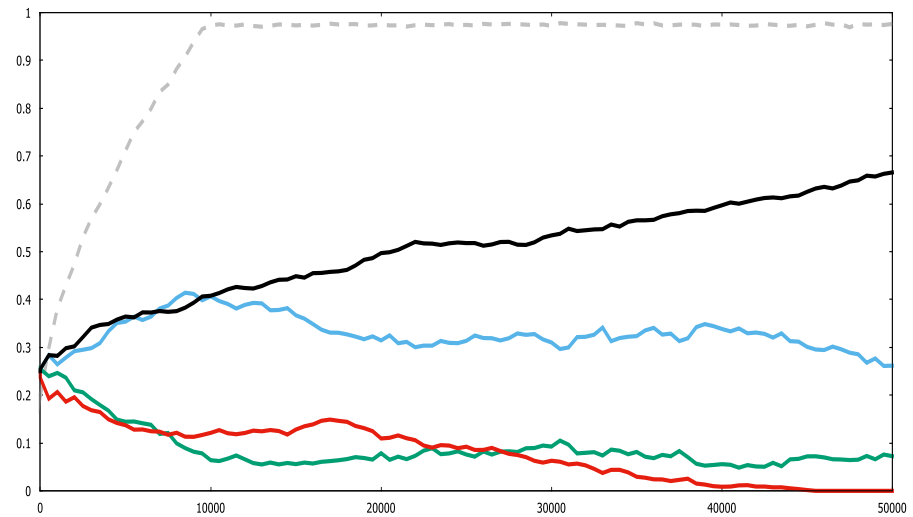
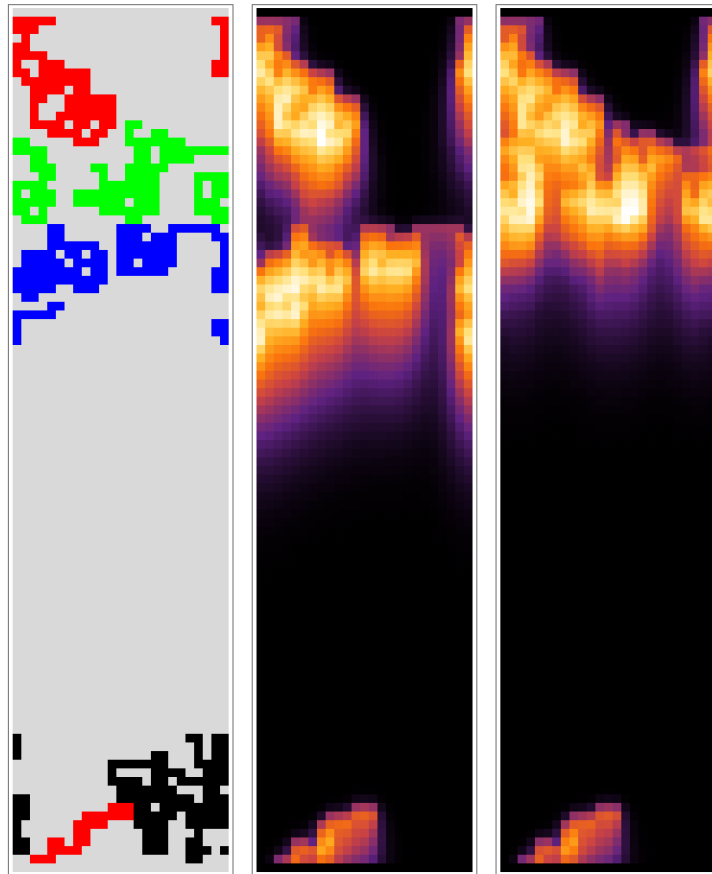
# IBM & Gradient model

## & Specialists – Generalist – Free-rider/Sensitive

Species	Diffusible resource produced (Public good)		Growth effect of the resource:	
	PG 1	PG 2	Antibiosis (-1)	Mutualism (1)
	→ 	→ 	<b>-1</b>	<b>1</b>
	→ 	→ 	<b>1</b>	<b>-1</b>
	→ 	→ 	<b>1</b>	<b>1</b>
	→ 	→ 	<b>-1</b>	<b>-1</b>

# IBM & Gradient model & Specialists – Generalist – Free-rider/Sensitive

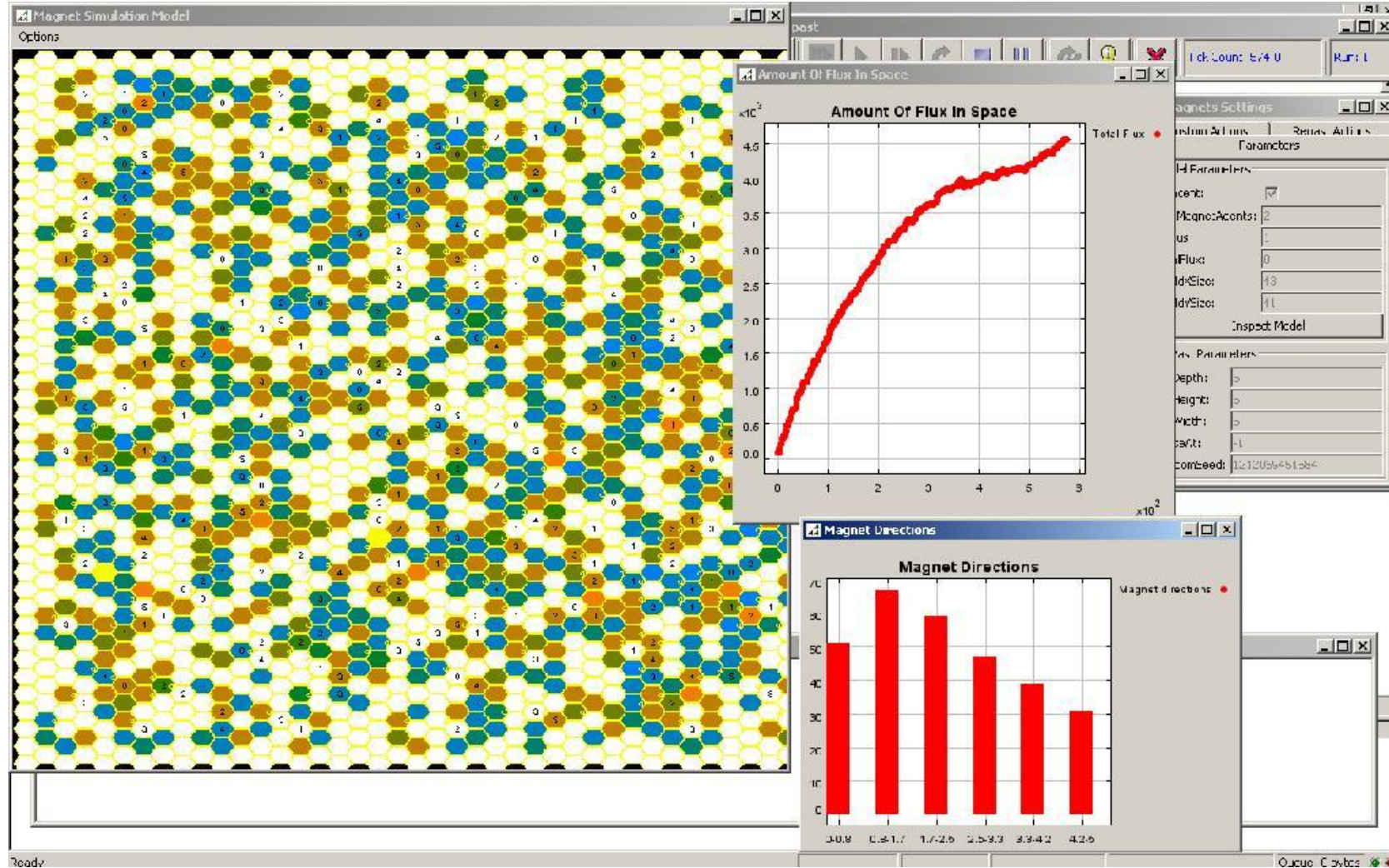
Gradient-oriented diffusion rate surplus = 0.25



# ABM platforms

- Specialized softwares: AnyLogic, NetLogo, Repast (Repast-HPC), Sesam, Swarm, etc.
  - + Lower entry barrier, graphical GUI, specialized libraries, online simulations
  - Slower simulation speed, limited scalability, limited capacity
- General-purpose programming languages: C, C++, Java, Julia, Pascal, MATLAB, Mathematica, Python
  - + Almost unlimited scalability (HPCs), debugging
  - Higher entry barrier, skills and time is necessary for coding, GUI is less easy to learn
- Combined solutions
  - Model in AnyLogic/NetLogo, output analysis in R
  - Model using specialized libraries of general-purpose languages (e.g., JAS-mine/ JAVA)
- ABM software comparison
  - [https://en.wikipedia.org/wiki/Comparison\\_of\\_agent-based\\_modeling\\_software](https://en.wikipedia.org/wiki/Comparison_of_agent-based_modeling_software)

# Repast (Java)



# NetLogo

The screenshot displays the NetLogo environment for a simulation titled "mutant1". The interface is organized into several key sections:

- Command Center:** Located at the bottom, it shows the "observer" prompt and a "Clear" button.
- Main View Area:** A large central window showing a 3D view of the simulation. It contains a grid of green patches and a population of blue turtles. A cluster of red 'x' marks represents mutants. The axes are labeled "year" and "x", with a "ticks: 0" indicator at the top.
- Control Panels:**
  - Buttons:** "setup" and "go" are at the top left.
  - Monitors:** "blue creatures" (364), "green patches" (304), "number mutants" (254), and "total turtles" (618).
  - Sliders:** "energy-from-grass" (8), "birth-energy" (45), "growth-rate" (10), "movement" (1), "new-birth-cost" (26), and "new-birth-energy" (50).
  - Toggle:** "show-energy?" is currently turned "On".
  - Other:** A "mutate turtle" button and a "slower" speed slider.
- Watch-me Window:** A window titled "mutant 121" provides detailed information for a selected turtle:

```
who 121
color 15
heading 242
xcor -4.205495806547415
ycor -5.093599129816123
shape "x"
label ""
label-color 9.9
breed mutants
hidden? false
size 1
pen-size 1
pen-mode "up"
energy 10
```

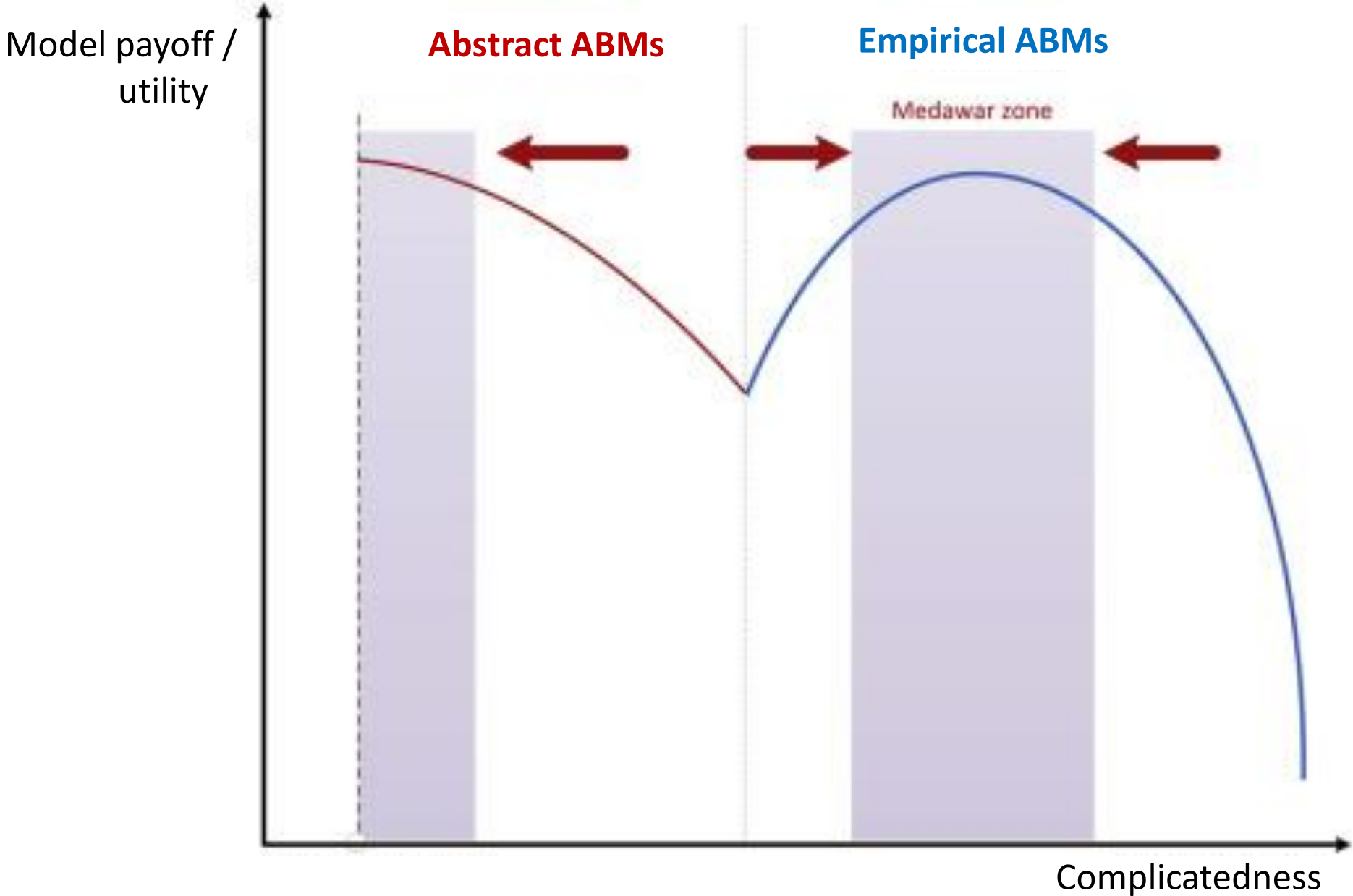
# ABM challenges

1. Optimize model complexity, choose the right modelling framework.
2. Compare ABMs and their results, predictions (problem of transparent and universal documentation).
3. Verify and validate ABMs.



# ABM challenges

## 1. Optimize model complexity:

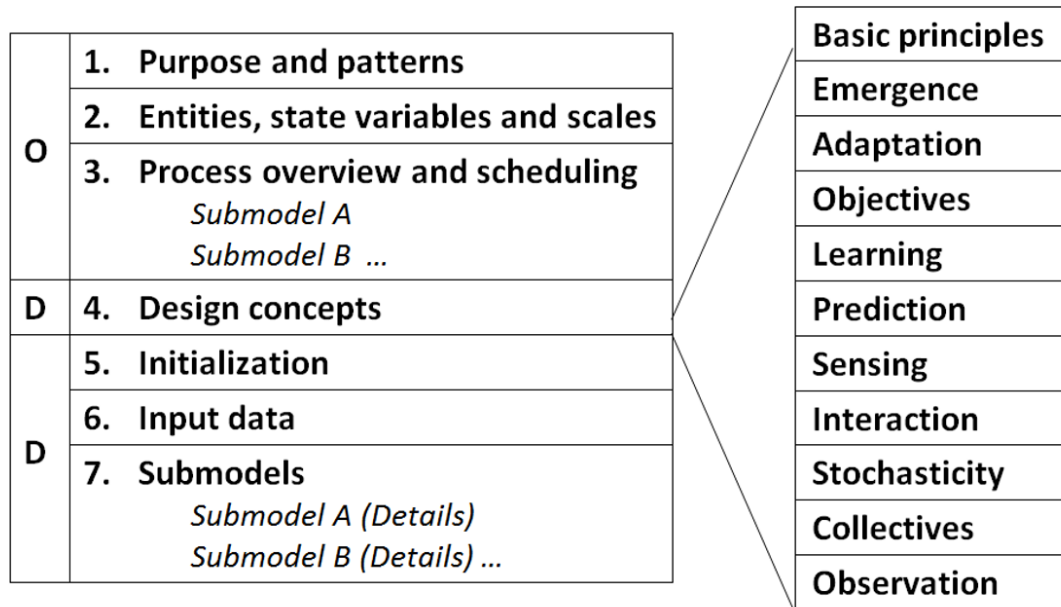


(Sun et al. 2016)

# ABM challenges

## 2. Compare ABMs:

transparent and universal documentation.



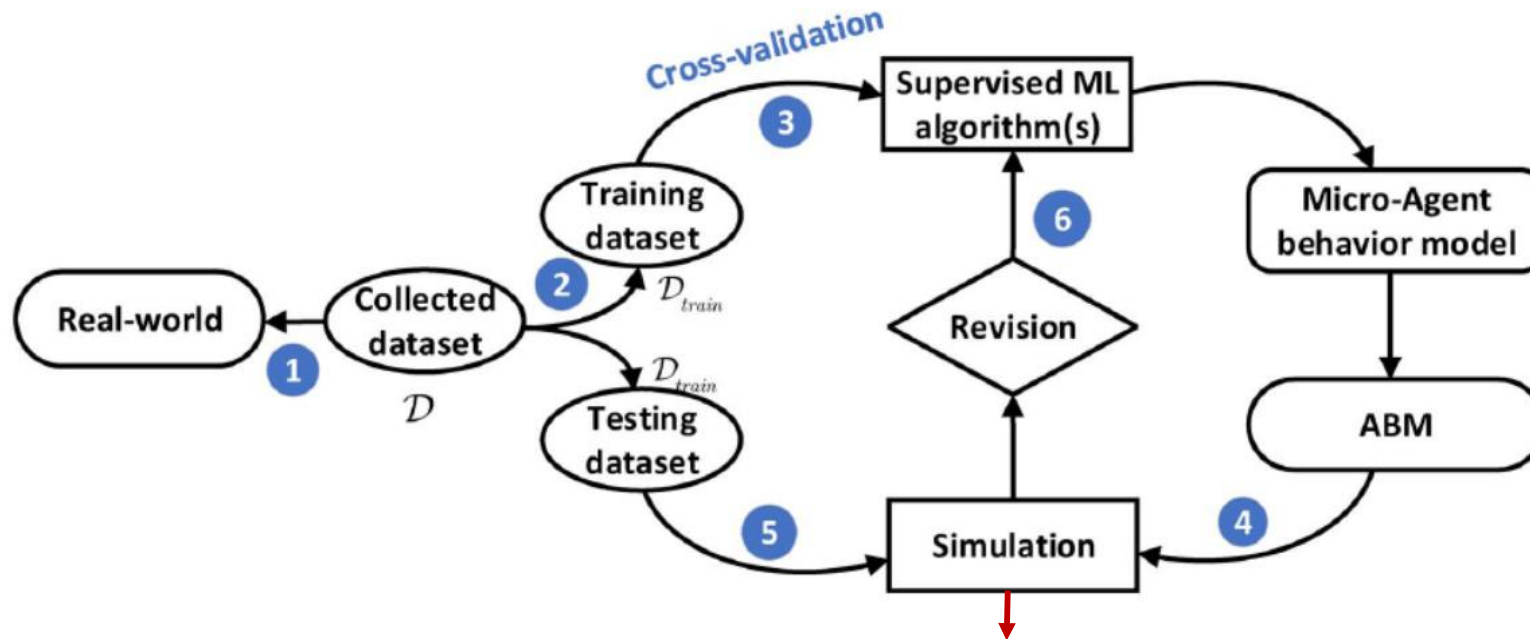
- Model code sharing
  - Specialised platforms
    - [comses.net](http://comses.net)
    - [cloud.anylogic.com](http://cloud.anylogic.com)
    - [runmycode.org](http://runmycode.org)
  - GitHub

# ABM challenges

## 3. Verify and validate ABMs.

Baseline behavior. Validate model with known parameters, retrieve published outcomes.

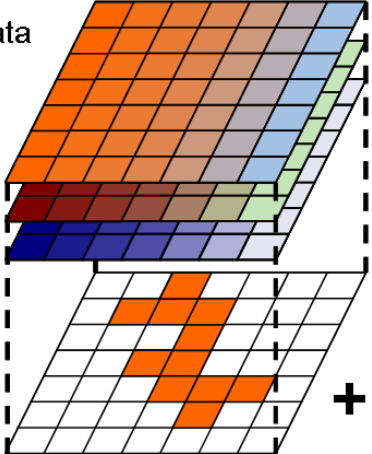
Data-driven modelling. Train functions, parameters, behavioral components with data.



# Complex ABM with multiple GIS Data layers

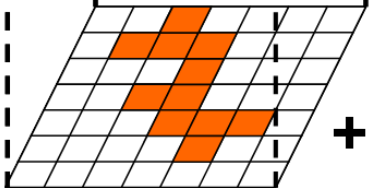
**GIS environmental data**

- Temperature
- Crops
- Precipitation

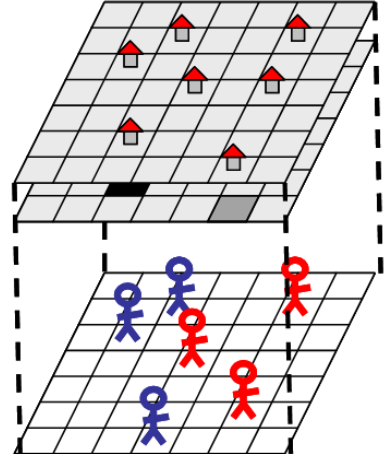


**Cellular automaton**

- Pest survival (T ; P ; crops)
- Pest dispersal (density)
- Pest fecundity (T)



+

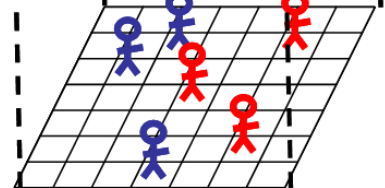


**GIS social data**

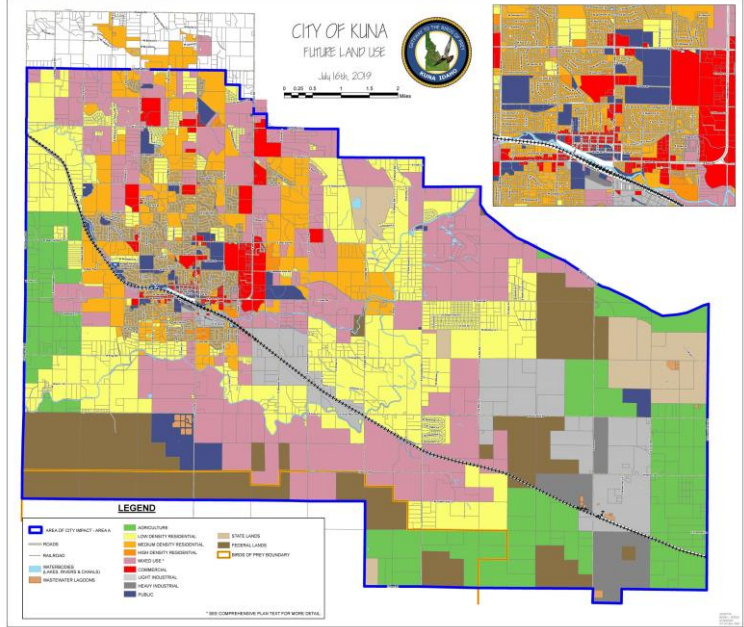
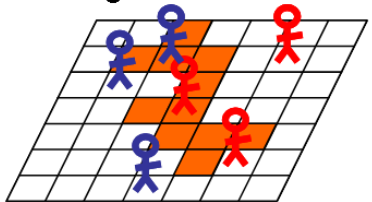
- Village location
- Population size

**Agents**

- Farmers - pest control knowledge
- team
- infestation state

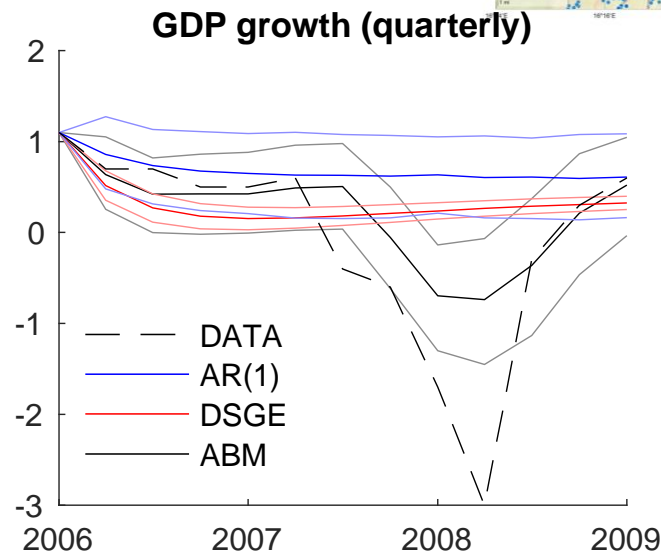
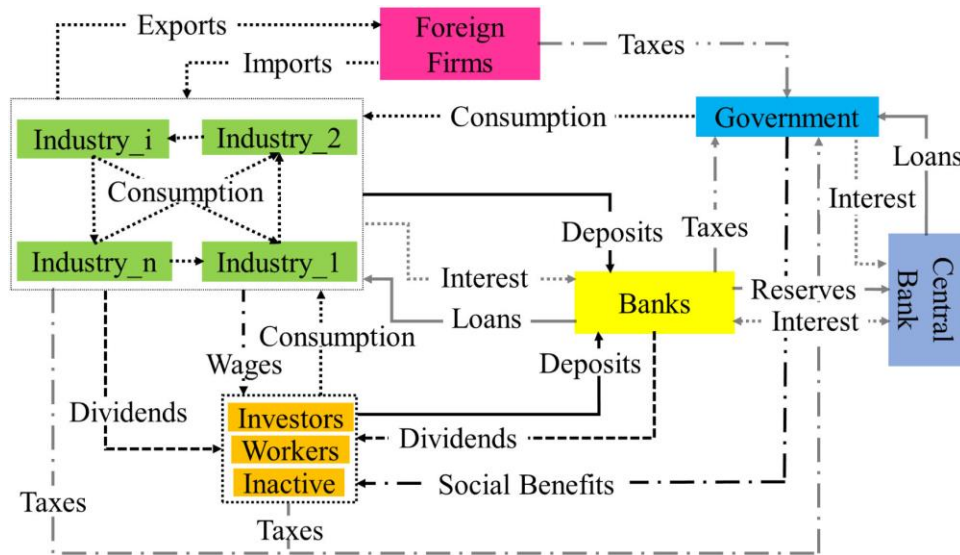
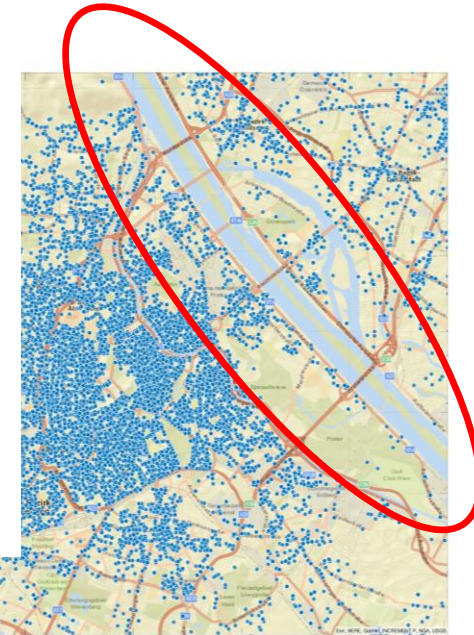
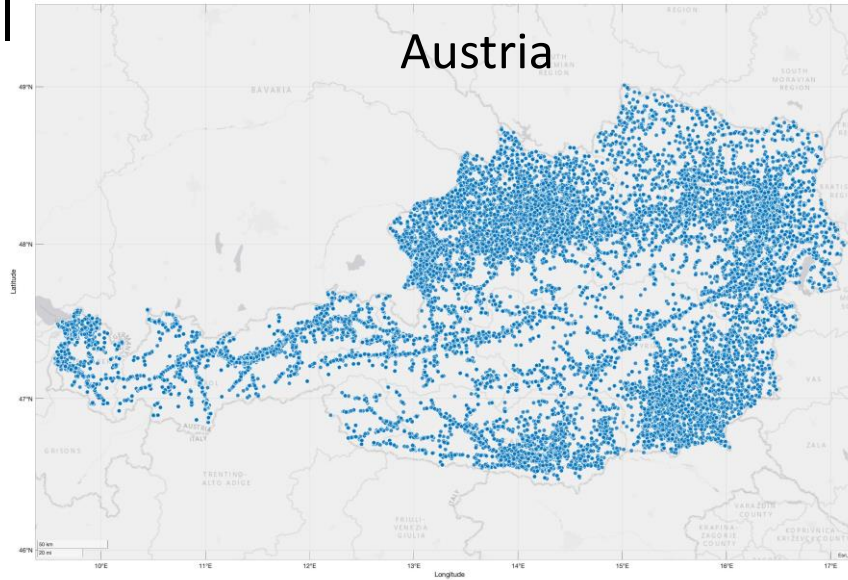


= Agent-Based Model



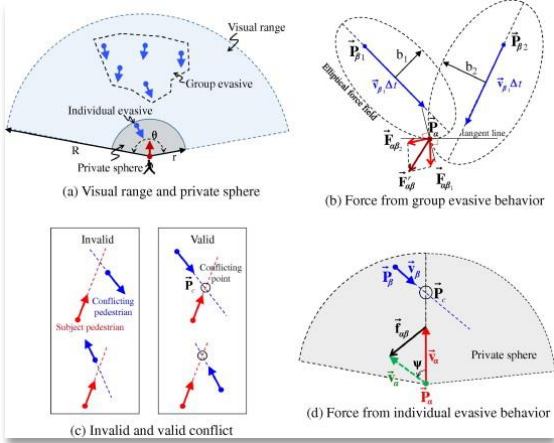
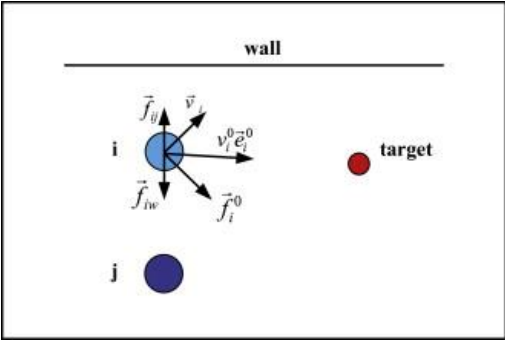
# Macroeconomic agent-based model for the macro-economy

- Agent-based model with explicit sector detail and millions of interacting agents;
- intersectoral input-output and financial linkages;
- calibrated micro- and macroeconomic pms;
- microfoundations for heterogeneous agents, financial frictions, and bounded rationality

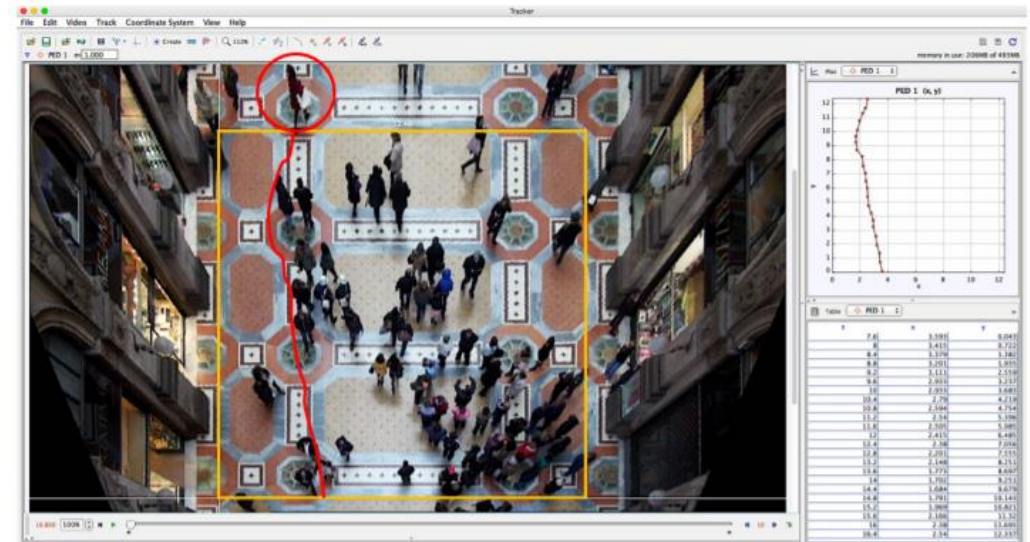
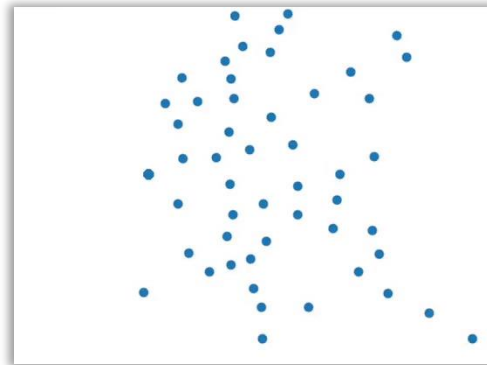
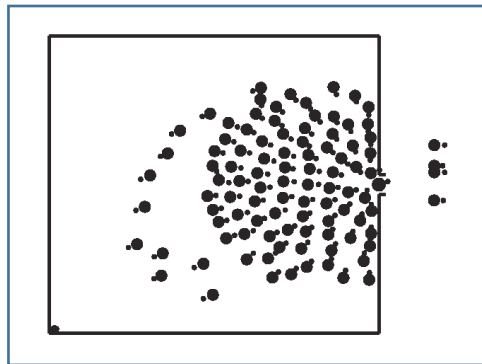
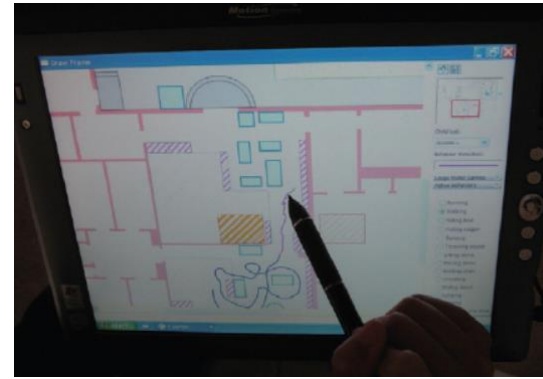
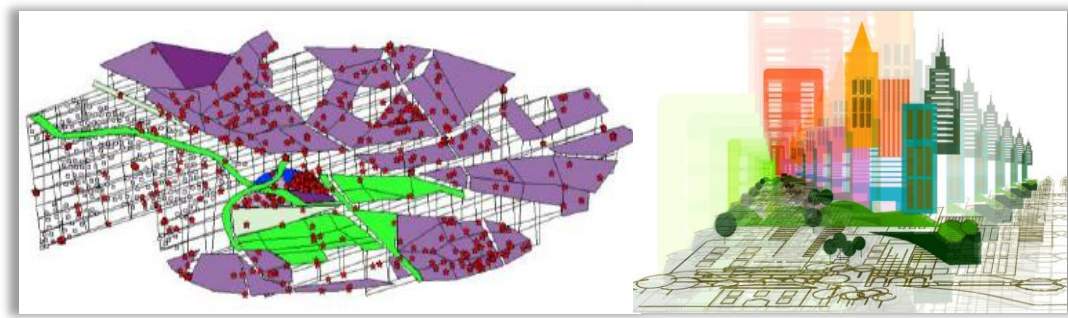
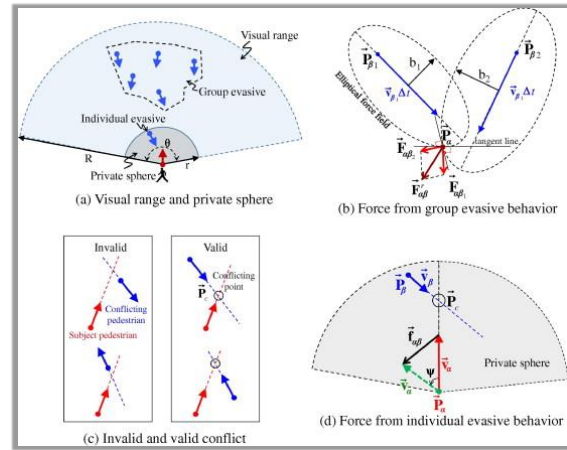
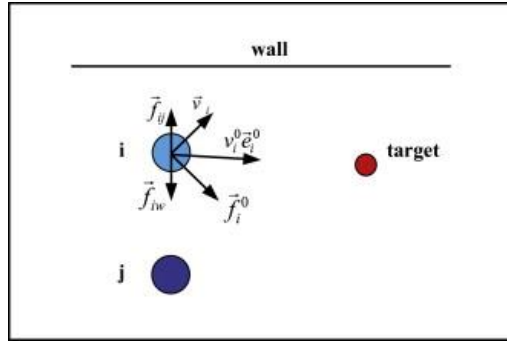


**ABM GDP forecasts from the last quarter of 2006 for the euro area**

# Social-force model: pedestrian behavior

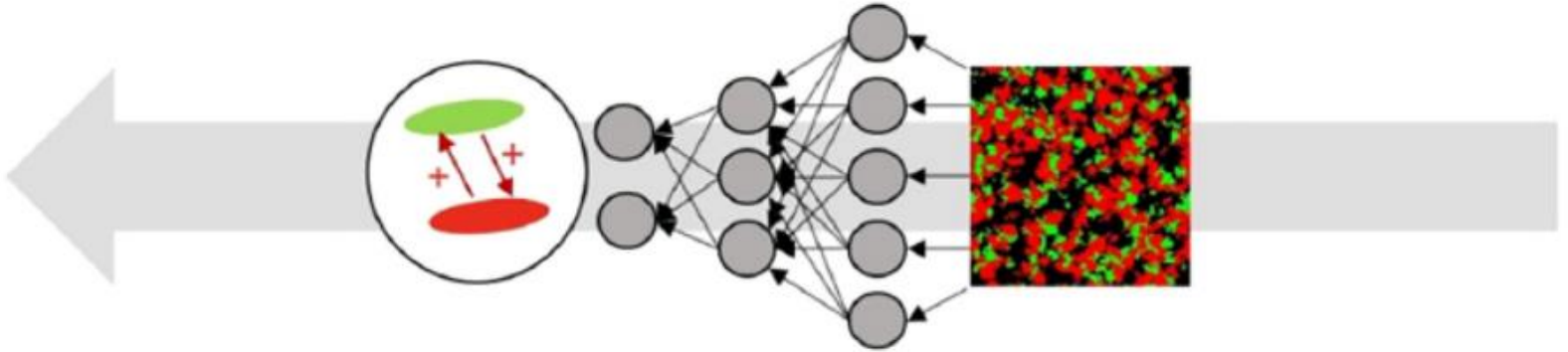
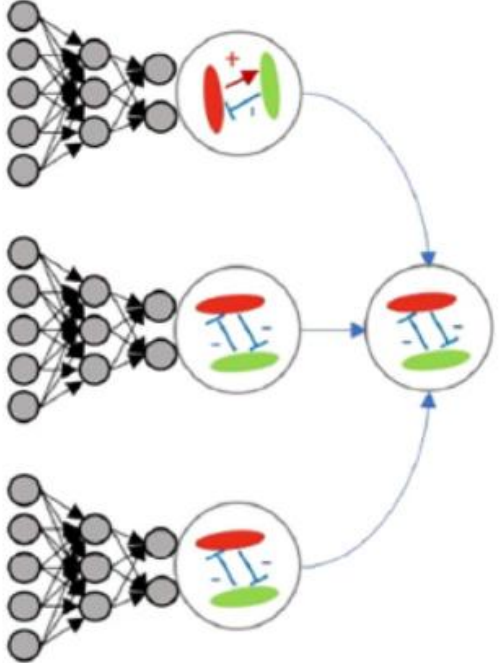
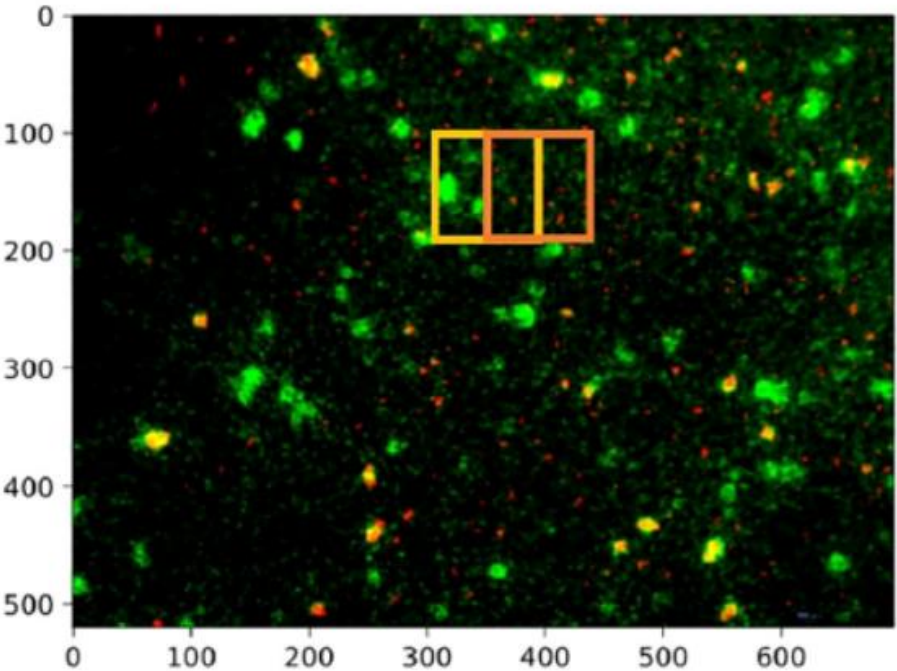


# Social-force model: pedestrian behavior



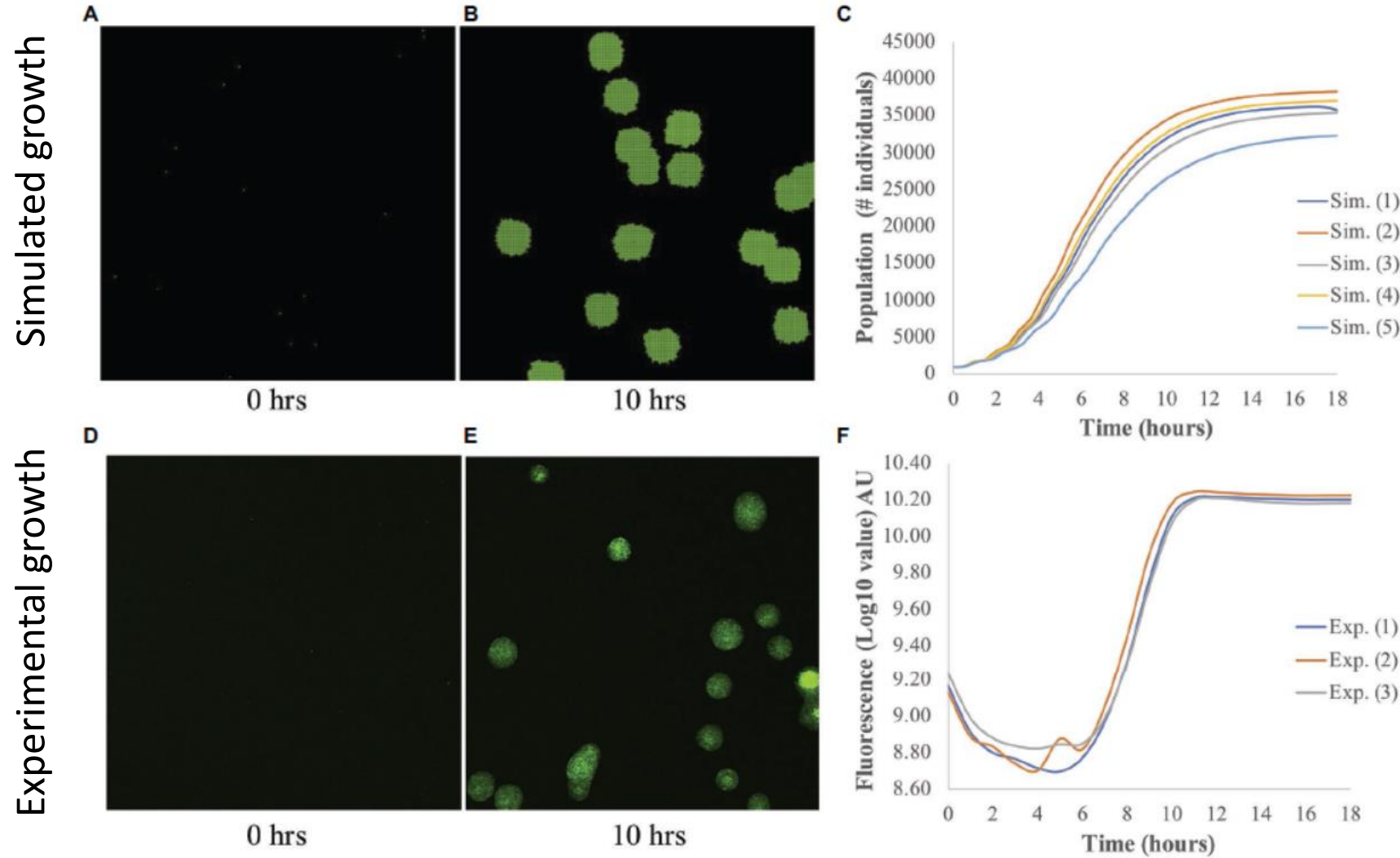
(Helbing and Molnár 1995; Johansson & Krietz 2011; Dam et al. 2014; Zeng et al. 2014; Gorrini et al. 2016; van Dam et al. smartctlab.web.illinois.edu; unalab.eu)

# ABM & Machine learning: understanding interaction networks





# ABM & Machine learning: parametrizing bacterial colony growth



Parameters	Description	Values [increment] (units)
<i>Efficiency</i>	Thermodynamic reactions efficiency	0.37 (-)*
<i>umax_pa</i>	Maximum growth rate of <i>Pantoea</i> individuals	0.1-10 [0.1] (hr <sup>-1</sup> )
<i>min/steptime</i>	Time-scalable conversion from ticks to minutes	0.1-2 [0.5] (min)
<i>diffusion-coefficient</i>	Rate of redistribution of nutrients on each patch at each steptime	0-1 [0.01] (-)*
<i>energy_maintenance_pa</i>	Minimum carbon needed by <i>Pantoea</i> to survive in time	0.0015 (g <sub>Glucose</sub> :g <sub>C<sub>pantoea</sub></sub> <sup>-1</sup> :h <sup>-1</sup> )
<i>rep_pa</i>	Minimum time needed by <i>Pantoea</i> to get ready for reproduction	20 (min)
<i>max-time-viability_pa</i>	Maximum time that <i>Pantoea</i> can survive without its minimum energy requirements	83 (min)
<i>pmax</i>	Maximum number of bacteria allowed in the same patch	1-10 [1] (#-patch <sup>-1</sup> )
<i>Ammonium</i>	Initial concentration of ammonium in patches	18.7 (mM)
<i>Glucose</i>	Initial concentration of glucose in patches	0-100 [0.1] (mM)
<i>Total-length-world</i>	Value of world width and world height	605 (μm)
<i>Depth</i>	Depth of the first "layer" of medium where the bacteria grow	10-50 [1] (μm)
<i>Microorganism</i>	Initial number of <i>Pantoea</i> individuals	10-1,000 [1] (#)

# Summary

- ABM is an extremely flexible modelling framework
- ABMs can be almost as complex as real life systems
- Very simple rules can recover patterns observed in the real world
- More than the sum of parts
- Modular structure, easy to develop further
- Unpredictable dynamics and resultant patterns: emergent behavior in a complex system

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**Thank you!**